A Theory of Fiscal Responsibility and Irresponsibility*

Marina Halac† Pierre Yared‡

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Abstract

We propose a political economy mechanism that explains the presence of fiscal regimes punctuated by crisis periods. Our model focuses on the interaction between successive deficit-biased governments subject to i.i.d. fiscal shocks. We show that the economy transitions between a fiscally responsible regime and a fiscally irresponsible regime, with transitions occurring during crises when fiscal needs are large. Under fiscal responsibility, governments limit their spending to avoid transitioning to fiscal irresponsibility. Under fiscal irresponsibility, governments spend excessively and precipitate crises that lead to the reinstatement of fiscal responsibility. Regime transitions can only occur if governments’ deficit bias is large enough.

Keywords: Private Information, Fiscal Policy, Deficit Bias

JEL Classification: C73, D02, D82, E6, H1, P16

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†Yale University, Department of Economics and CEPR. Email: marina.halac@yale.edu.

‡Columbia University, Graduate School of Business and NBER. Email: pyared@columbia.edu.
1 Introduction

Fiscal policy in practice cannot be explained by normative considerations alone. Political forces also appear to play a role. At long frequencies, the historical accumulation of government debt across advanced economies is not fully accounted for by normative models, but is consistent with long-term political trends and political economy incentives that promote greater debt accumulation (e.g., Alesina and Passalacqua, 2016; Yared, 2019). At short frequencies, research has found that debt accumulation is partly driven by the electoral cycle (e.g., Drazen, 2000; Müller, Storesletten, and Zilibotti, 2016) and is correlated with the government’s party identity, patterns that are consistent with models of party competition and political turnover.¹

Our focus in this paper is on fiscal policy at intermediate frequencies, spanning multiple political and economic cycles. The stance of fiscal policy, particularly in advanced economies, cannot be explained by contemporaneous macroeconomic variables. For example, there is evidence that taxes and spending exhibit persistence above and beyond that of the GDP and the level of debt.² Studies also find that persistent changes in the stance of fiscal policy tend to be preceded by crisis periods.³

The trajectory of government debt in the U.S. since 1970 displays these dynamics. Figure 1 shows U.S. public debt as a percent of GDP since 1945. The OPEC oil embargo of 1973, the Iranian Revolution of 1979, and the Volcker disinflation of 1980 ended a decades-long decline in public debt after World War II, with government debt to GDP increasing by 38 percent over the course of three recessions between 1974 and 1983. This debt expansion persisted during the 1980s economic boom under the Reagan administration and into the 1990 recession and First Gulf War, after which a combination of tax increases and spending cuts under the Bush and Clinton administrations decelerated and eventually turned negative the growth rate of debt to GDP. This decline in debt was halted after the 2001 recession and the onset of the War on Terror, with an eventual explosion of debt during the Global Financial Crisis of

¹In advanced economies, Müller, Storesletten, and Zilibotti (2016) find that while a shift from left-leaning to right-leaning governments results in more debt accumulation, left-leaning governments accumulate more debt during recessions. Sachs (1990) and Dornbusch and Edwards (1991) document that left-leaning governments in Latin America increase debt by more than right-leaning ones.

²See for example the analysis of Afonso, Agnello, and Furceri (2010) and Jiang et al. (2021).

³Cassou, Shadmani, and Vázquez (2017), Aldana and Creel (2019), and Elenev et al. (2021) find that U.S. fiscal policy can be characterized by two different fiscal regimes. Cassou, Shadmani, and Vázquez (2017) find evidence that a negative output gap increases the chance of transitioning out of one regime to the other (see their Table 1).
Figure 1: Federal debt held by the public as percent of GDP. Shaded areas indicate U.S. recessions. Sources: OMB; St. Louis Fed. Retrieved from FRED: https://fred.stlouisfed.org/series/FYGFGDQ188S.

2008. This crisis in turn ushered in a new period of fiscal consolidation, with spending limits established under the Budget Control Act of 2011 helping to decelerate the debt growth. More recently, in the aftermath of the COVID-19 pandemic following the roll-out of the vaccines in the spring of 2021, Congress favored a loose stance of fiscal policy with a historically large stimulus.

In this paper, we propose a political economy mechanism that explains the presence of fiscal regimes punctuated by crisis periods, as those in Figure 1. Our model focuses on the dynamic interaction between successive deficit-biased governments subject to i.i.d. fiscal shocks. We show that the economy endogenously transitions between a fiscally responsible regime and a fiscally irresponsible regime, with transitions occurring during crises when fiscal needs are large. In the fiscally responsible regime, governments limit their spending in order to avoid transitioning to fiscal irresponsibility. In the fiscally irresponsible regime, governments spend excessively even relative to their biases, precipitating crises that lead to the reinstatement of fiscal responsibility.

Our environment is an infinite horizon small open economy in which successive governments make borrowing decisions. Prior to the choice of policy at every date,
an i.i.d. shock to the social value of deficit-financed government spending is realized. Governments are deficit-biased: for any given shock, the government overvalues current spending relative to future welfare compared to society. This bias captures the fact that governments in power can obtain private benefits from spending, for example by diverting resources towards their preferred spending categories or constituencies (e.g., Aguiar and Amador, 2011). Additionally, we assume that the shock to the value of spending in each period is privately observed by the government in power in that period. As discussed in Section 2, this may reflect governments having superior information about the cost of public goods or aggregate citizen preferences. More broadly, this assumption says that current policy does not depend on past fiscal needs above and beyond what is captured by past policy decisions; such needs are difficult to quantify relative to observable fiscal variables.

An equilibrium in our setting prescribes a level of borrowing for each government in each period. This level of borrowing is a function of the government’s observed shock and the history of past borrowing decisions. While multiple equilibria may arise, we focus on the best equilibrium for society, namely the one that maximizes social welfare at the beginning of time. We provide a recursive representation of this equilibrium and study its properties.

To describe the forces underlying our model, consider first what would happen in the absence of either a deficit bias or private information. If governments are not biased towards current spending, then trivially the best equilibrium has each government choosing the first-best policy (i.e. the policy that maximizes social welfare in each period), even if shocks to the value of spending are private information. Moreover, because shocks are i.i.d., fiscal policy (conditional on debt) features no history-dependence.

If governments are deficit-biased but fiscal shocks are publicly observable, the best equilibrium maximizes social welfare subject to a limited commitment constraint. This constraint requires that for each shock, each government prefer its prescribed level of borrowing and continuation value to any other borrowing level. Since all deviations are public, they are punished (off path) with the lowest possible continuation value conditional on the government’s choice of debt. The best equilibrium prescribes the first-best policy if this limited commitment constraint does not bind, or the lowest enforceable borrowing level if the constraint binds. In either case, the equilibrium restarts in each period, so fiscal policy again features no history-dependence.
Our setting combines both a deficit bias and private information. Because governments cannot directly condition their policy choices on past shocks under private information, the limited commitment constraint described above is insufficient: a government can now deviate privately from its prescribed policy and choose a higher borrowing level without being penalized with a low continuation value. The best equilibrium in this setting therefore maximizes social welfare subject to not only the limited commitment constraint but also a private information constraint: for each government and shock, the government must prefer its prescribed level of borrowing and continuation value to those prescribed for any other shock.

We show that the best equilibrium is characterized by a fiscally responsible low-deficit regime that maximizes social welfare and a fiscally irresponsible high-deficit regime that minimizes social welfare, with transitions between regimes being triggered by high enough fiscal shocks. The threat of transitioning to the fiscally irresponsible regime sustains the fiscally responsible regime, and the promise of returning to the fiscally responsible regime sustains the fiscally irresponsible regime. Moreover, unlike under observable shocks, temporary transitions from one regime to the other may occur on path, and fiscal policy therefore is history-dependent.

Our characterization shows that fiscal policy in each regime admits a simple form. The fiscally responsible regime takes the form of a maximally enforced deficit limit. If a government chooses borrowing below the limit, the equilibrium restarts in the fiscally responsible regime in the next period. If instead a government violates the limit, the equilibrium transitions to the fiscally irresponsible regime. Governments may be unconstrained by the deficit limit when experiencing low shocks, but they are constrained under high shocks, and in some cases they break the limit. Moreover, fiscal policy is unresponsive to economic conditions when governments are constrained but respect the limit.

The fiscally irresponsible regime takes the form of a maximally enforced surplus limit. If a government chooses borrowing above the limit, the equilibrium returns to the fiscally responsible regime in the next period. If instead a government violates the limit, the equilibrium restarts in the fiscally irresponsible regime. Governments are unconstrained by the surplus limit when experiencing high shocks, but they are constrained under low shocks, and in some cases they break the limit. The fiscally irresponsible regime can be interpreted as a temporary abandonment of deficit limits, with fiscal responsibility being reinstated only when the deficit becomes large enough.
A key feature of our environment is that while governments overweigh present spending, they share the same preferences as society for fiscal responsibility in the future. Thus, a maximally enforced deficit limit maximizes social welfare by countering the political bias to overborrow: governments are rewarded for choosing low borrowing with a fiscally responsible continuation regime and are punished for choosing high borrowing with a fiscally irresponsible continuation regime. Similarly, a maximally enforced surplus limit—which serves as a punishment—minimizes social welfare by inducing governments to follow their biases. Punishment is always temporary, since a government’s overborrowing is rewarded with a transition back to fiscal responsibility.

Our analysis sheds light on the empirical path of fiscal policy at intermediate frequencies. Periods of fiscal consolidation can be understood as fiscally responsible behavior by governments which realize that deviating from such behavior would set a precedent for deviations by subsequent governments. As such, periods of fiscal consolidation end when shocks are sufficiently severe that the cost of setting this negative precedent is outweighed by the benefit of responding to current economic conditions. Analogously, periods of debt buildup can be understood as fiscally irresponsible behavior by governments which derive benefits from current spending and realize that future fiscal consolidations will occur once deficits become large enough following severe shocks. These dynamics imply that fiscal policy depends on the history and cannot be explained by contemporaneous variables alone, and that persistent changes in fiscal policy are punctuated by crisis periods.

Regime transitions are consistent with the evidence cited above and with the 1970-2020 evolution of U.S. public debt shown in Figure 1. As the figure shows, however, things are different between World War II and 1970: debt to GDP follows a downward trajectory and does not appear to exhibit regimes over that earlier period. What explains the difference? To provide insight into this question, we study the conditions for regime transitions in the context of an analytical example. We show that fiscal regimes can arise only if governments’ bias towards current spending is sufficiently large; furthermore, for a range of such biases, regime transitions occur on path in the best equilibrium. Intuitively, as the governments’ deficit bias increases, the threat of fiscal irresponsibility in the future also increases, making it possible to sustain a regime of fiscal responsibility in the present.

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Specifically, we examine a setting in which the social value of government spending takes a log form, which allows us to characterize the best equilibrium as a fixed point of an operator function.
Altogether, our results suggest that the emergence of regimes since the 1970s may be partly explained by an increase in governments’ deficit bias relative to the earlier period. Such an increase in governments’ deficit bias and its effect on rising debt levels across advanced economies have been documented in the political economy literature. Our paper shows that increased biases lead not only to higher long-run debt growth but also to the emergence of regimes in fiscal policy.

**Related literature.** Our paper contributes to the literature on the political economy of government debt. This literature has emphasized how certain forces such as political risk, polarization, and demographics cause governments to accumulate more debt than is socially optimal (see fn. 5.) Dynamic models related to ours include Battaglini and Coate (2008), Yared (2010), and Dovis, Golosov, and Shourideh (2016). Unlike these papers, we study a setting that features private government information and yields fiscal policy regimes, and we examine how the emergence of regimes depends on the underlying political economy frictions.

A growing literature studies the impact of private government information for policy. Within this literature, our paper relates to work on the tradeoff between commitment and flexibility in policymaking, including Athey, Atkeson, and Kehoe (2005), Amador, Werning, and Angeletos (2006), and Halac and Yared (2014, 2022). Our results pertaining to the fiscally responsible regime use tools developed in Halac and Yared (2022), which examines optimal fiscal rules under private information and limited enforcement. That paper considers a static model with exogenously enforced penalties, whereas here we study a dynamic model in which any punishments must be self-enforced by future equilibrium behavior. Also related are Halac and Yared (2020, 2021), which apply similar tools to monetary policy settings with no state variables.

By studying the welfare-maximizing policy for present-biased governments, our

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5See Alesina and Passalacqua (2016) and Yared (2019) for surveys. Yared (2019) argues that an increasingly older population, rising political polarization, and rising electoral uncertainty have led to increased political biases across advanced economies.

6Battaglini and Coate (2008) and Dovis, Golosov, and Shourideh (2016) analyze Markov perfect equilibria, in which policy therefore does not inherit more persistence than payoff relevant state variables. Yared (2010) analyzes the efficient sustainable equilibrium which admits $S,s$ rules for policy and therefore more persistence than in Markov perfect equilibria, but this persistence dissipates after one period.


8The claims in Halac and Yared (2020) (which contains no proofs) rely on the results presented in Section 4 of the present paper and their proofs.
analysis contributes to the literature on hyperbolic discounting that builds on Phelps and Pollak (1968) and Laibson (1994, 1997). Recent related papers include Bernheim, Ray, and Yeltekin (2015), Bisin, Lizzeri, and Yariv (2015), and Lizzeri and Yariv (2017). Bernheim, Ray, and Yeltekin (2015) find that the optimal self-enforcing rule for a consumer with quasi-hyperbolic preferences entails temporary overspending as punishment. However, their setting has no private information, and as such punishment never occurs along the equilibrium path.

The regime dynamics in our model are reminiscent of the analysis of price wars in Green and Porter (1984) and more broadly related to the dynamics of repeated games in Abreu, Pearce, and Stacchetti (1990) and Sannikov (2007). These papers consider repeated moral hazard settings with finite actions (and thus finite incentive constraints) and a continuum of shocks, and therefore their techniques do not apply to our problem which features adverse selection and a continuum of actions and shocks. Athey, Bagwell, and Sanchirico (2004) study related issues in a repeated Bertrand game with private information.

Finally, the approach that we use to examine the analytical example of Section 5 resembles the factorization algorithm of Abreu, Pearce, and Stacchetti (1990) but for our adverse selection problem. Exploiting the single-dimensionality of the value set in our setting, we are able to characterize the best equilibrium as a fixed point of an operator function. In contrast to Abreu, Pearce, and Stacchetti (1990), we apply the algorithm starting from the smallest rather than the largest set, providing necessary conditions for the convergence to a fixed point that exceeds the Markov outcome. This method might potentially be useful in other games to determine when the Markov outcome can be improved upon.

2 Model

We present a simple model in which successive governments make borrowing decisions. We describe our setup in Subsection 2.1, define our equilibrium concept in Subsection 2.2, and provide a recursive representation of the welfare-maximizing equilibrium in Subsection 2.3.

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9See also Strotz (1956) and Calvo and Obstfeld (1988) for a related treatment of dynamically-inconsistent government preferences.

10See also Phelan and Stacchetti (2003).
2.1 Setup

Consider an infinite horizon small open economy with periods \( t = \{0, 1, \ldots \} \) and a different government in each period. At the beginning of each period \( t \), an i.i.d. shock to the economy \( \theta_t > 0 \) is drawn from a bounded set \( \Theta \equiv [\underline{\theta}, \overline{\theta}] \), with a continuously differentiable probability density function \( f(\cdot) > 0 \) and associated cumulative density function \( F(\cdot) \). The realization of this shock is privately observed by the government in power at date \( t \), so we refer to \( \theta_t \) as this government’s type.

We denote by \( b_t \geq 0 \) and \( g_t \geq 0 \) respectively the government’s choices of debt and spending at date \( t \). The government’s budget constraint is given by

\[
g_t = \tau - Rb_{t-1} + b_t, \tag{1}
\]

where \( \tau > 0 \) is the exogenous tax revenue and \( R > 1 \) is the exogenous gross interest rate on government bonds.

Social welfare at date \( t \) is

\[
V_t = \mathbb{E}_t \left[ \sum_{k=0}^{\infty} \delta^k \theta_{t+k} U(g_{t+k}) \right],
\]

or equivalently, rewriting it recursively,

\[
V_t = \mathbb{E}_t [\theta_t U(g_t) + \delta V_{t+1}].
\]

Here \( \delta \in (0, 1) \) denotes the social discount factor and \( U(\cdot) \) is the utility of government spending, which we assume to be strictly increasing and strictly concave. Observe that a large shock \( \theta_t > 0 \) implies a large social value of government spending, as would be the case for example in an economic crisis.

The welfare of the government at date \( t \), when choosing policy following the realization of \( \theta_t \), is

\[
\alpha \theta_t U(g_t) + \delta V_{t+1}, \tag{2}
\]

where \( \alpha > 1 \) represents the government’s deficit bias.

There are three main features of our environment. First, since \( \alpha > 1 \), government preferences differ from those of society. The bias \( \alpha \) captures the fact that a government in power at date \( t \) derives private benefits from spending at \( t \), for example by being able to divert resources towards its preferred spending categories or towards a political
constituency. The government at date $t$ however shares the same preferences as society from date $t + 1$ onward, as it does not receive any private benefits from spending in the future when it is no longer in power.

The second feature of our environment is that the shock $\theta_t$ is privately observed by the government at date $t$ (and thus not observed by future governments). One interpretation is that the exact cost of public goods at $t$ is only observable to the government in office, which may be inclined to overspend on these goods. Another possibility is that citizens have heterogeneous preferences or heterogeneous information about the optimal level of public spending, and only the current government sees the aggregate (Sleet, 2004; Piguillem and Schneider, 2016). A final possibility is that future governments observe $\theta_t$ but do not condition their behavior directly on this past realization, for example because it is not as easily quantifiable as the history of fiscal variables that do inform their behavior.

The third feature of our environment is that governments have full discretion when choosing policy. At each date $t$, the government is able to freely choose any level of debt, subject only to feasibility as we describe next. Without any exogenously enforced incentives, it is only the behavior of future governments which can serve as reward and punishment for a government’s policy decisions.

We complete the description of our environment with a technical constraint. We require the level of debt in each period $t$ to satisfy $b_t \in [\underline{b}(b_{t-1}), \overline{b}(b_{t-1})]$ for some $\underline{b}(b_{t-1}) > Rb_{t-1} - \tau$ and $\overline{b}(b_{t-1}) < \tau/(R - 1)$. These bounds guarantee that payoffs are bounded, and we take them to be wide enough that this constraint is otherwise non-binding.

We also assume that the initial level of debt at time 0, which is exogenous, satisfies $b_{-1} < \tau/(R - 1)$.

### 2.2 Equilibrium Definition

We consider the interaction between the successive governments in each period $t = \{0, 1, \ldots\}$. Let $h^{t-1} = \{b_{-1}, b_0, \ldots, b_{t-1}\}$ denote the history of debt through time $t-1$ and $\mathcal{H}^{t-1}$ the set of all possible such histories. A strategy for the government in period $t$ is $\sigma_t(h^{t-1}, \theta_t)$, specifying, for each history $h^{t-1} \in \mathcal{H}^{t-1}$ and government type $\theta_t \in \Theta$, a feasible level of debt $b_t(h^{t-1}, \theta_t)$. Note that given the budget constraint (1), a history of debt also pins down the history of spending, and the government’s

\[[11] See Laibson (1994) for further discussion of the necessity of these bounds in the quasi-hyperbolic model.\]
strategy also pins down its choice of spending. Specifically, denoting the available resources at history $h_{t-1}$ by

$$\omega_t(h_{t-1}) \equiv \tau - Rb_{t-1}(h_{t-1}),$$

spending given $h_{t-1}$ and $\theta_t$ is $g_t(h_{t-1}, \theta_t) = \omega_t(h_{t-1}) + b_t(h_{t-1}, \theta_t)$.

An equilibrium is defined as a profile of strategies $\sigma = (\sigma_t(h_{t-1}, \theta_t))_{t=0}^\infty$ such that, for each $t \in \{0, 1, \ldots\}$, $\sigma_t(h_{t-1}, \theta_t)$ maximizes the date-$t$ government’s welfare (2) given the continuation strategies $(\sigma_{t+k}(h_{t+k-1}, \theta_{t+k}))_{k=1}^\infty$ of all future governments. Given an equilibrium, let $V_t(h_{t-1})$ denote the continuation value to society at date $t$ starting from (on- or off-path) history $h_{t-1}$. This continuation value can be represented recursively as

$$V_t(h_{t-1}) = \mathbb{E}_t[\theta_t U(\omega_t(h_{t-1}) + b_t(h_{t-1}, \theta_t)) + \delta V_{t+1}(h_{t-1}, b_t(h_{t-1}, \theta_t))].$$

A profile of strategies $(\sigma_t(h_{t-1}, \theta_t))_{t=0}^\infty$ constitutes an equilibrium if and only if it satisfies the governments’ private information and limited commitment constraints for all $t \in \{0, 1, \ldots\}$ and all (on- and off-path) histories $h_{t-1}$. The private information constraint captures the fact that the government at any date $t$ can deviate privately by choosing a level of borrowing prescribed for a type different from its own. To guarantee that a government of type $\theta_t$ prefers to pursue its prescribed level of borrowing rather than that of any other type $\theta'_t \neq \theta_t$, we must have

$$\alpha \theta_t U(\omega_t(h_{t-1}) + b_t(h_{t-1}, \theta_t)) + \delta V_{t+1}(h_{t-1}, b_t(h_{t-1}, \theta_t)) \geq \alpha \theta_t U(\omega_t(h_{t-1}) + b_t(h_{t-1}, \theta'_t)) + \delta V_{t+1}(h_{t-1}, b_t(h_{t-1}, \theta'_t))$$

for all $\theta_t, \theta'_t \in \Theta$.

The limited commitment constraint captures the fact that the government at any date $t$ can deviate publicly by choosing a level of borrowing not prescribed for any type. To guarantee that a government of type $\theta_t$ prefers to pursue its prescribed level of borrowing rather than any other level of borrowing $b'_t$ satisfying $b'_t \neq b_t(h_{t-1}, \theta'_t)$ for all $\theta'_t \in \Theta$, we must have

$$\alpha \theta_t U(\omega_t(h_{t-1}) + b_t(h_{t-1}, \theta_t)) + \delta V_{t+1}(h_{t-1}, b_t(h_{t-1}, \theta_t)) \geq \alpha \theta_t U(\omega_t(h_{t-1}) + b'_t) + \delta V_{t+1}(h_{t-1}, b'_t)$$
for all \( \theta_t \in \Theta \) and all \( b'_t \) satisfying \( b'_t \neq b_t(h^{t-1}, \theta'_t) \) for all \( \theta'_t \in \Theta \).

Since debt is bounded and shocks are i.i.d., there exists an upper bound \( \overline{V}(b_t) \) that corresponds to the highest continuation value that can be sustained by equilibrium strategies conditional on debt \( b_t \), with \( V_{t+1}(h^{t-1}, b'_t) \leq \overline{V}(b'_t) \) for all \( h^{t-1} \) and \( b'_t \). By analogous logic, there also exists a lower bound \( \underline{V}(b_t) \), with \( V_{t+1}(h^{t-1}, b'_t) \geq \underline{V}(b'_t) \) for all \( h^{t-1} \) and \( b'_t \). Given available resources \( \omega_t(h^{t-1}) \), let \( b_p^t(\omega_t(h^{t-1}), \theta_t) \) denote type \( \theta_t \)'s flexible level of debt conditional on being punished with this lowest continuation value:

\[
b_p^t(\omega_t(h^{t-1}), \theta_t) \in \arg \max_{b_t \in [b_t(h^{t-1}), \overline{b}(b_{t-1})]} \{ \alpha \theta_t U(\omega_t(h^{t-1}) + b_t) + \delta \overline{V}(b_t) \}. \tag{5}
\]

Note that satisfying the limited commitment constraint (4) requires that the constraint hold under maximal punishment, namely when \( V_{t+1}(h^{t-1}, b'_t) = \overline{V}(b'_t) \). In fact, since the inequality must then hold for all \( b'_t \in [b_t(h^{t-1}), \overline{b}(b_{t-1})] \), it must necessarily hold when \( b'_t = b_p^t(\omega_t(h^{t-1}), \theta_t) \). Thus, a necessary condition for the limited commitment constraint to be satisfied is

\[
\alpha \theta_t U(\omega_t(h^{t-1}) + b_t(h^{t-1}, \theta_t)) + \delta V_{t+1}(h^{t-1}, b_t(h^{t-1}, \theta_t)) \\
\geq \alpha \theta_t U(\omega_t(h^{t-1}) + b_p^t(h^{t-1}, \theta_t)) + \delta \overline{V}(b_p^t(\omega_t(h^{t-1}), \theta_t)) \tag{6}
\]

for all \( \theta_t \in \Theta \), where the right-hand side is the government’s minmax payoff.

Constraints (3) and (6) are clearly necessary for a sequence of debt to be supported by equilibrium strategies. Furthermore, these constraints are also sufficient: if a sequence of debt satisfies (3) and (6), then it can be supported by a strategy profile that specifies the worst feasible continuation equilibrium following any public deviation. Since such a deviation is off path, it is without loss to assume that it is maximally punished.

We define the best equilibrium for society as the equilibrium that maximizes date-0 social welfare \( V_0(b_{-1}) \) given initial debt \( b_{-1} \).

### 2.3 Recursive Representation

Given the repeated nature of the game and the fact that shocks are i.i.d., we can represent policies in the best equilibrium recursively (see Abreu, Pearce, and Stachetti, 1990; Chade, Prokopovych, and Smith, 2008). That is, rather than optimizing
over an entire debt sequence, starting from any given date, we can assign each type \( \theta \in \Theta \) of the government a level of debt \( b(\theta) \) and continuation value \( V(b(\theta)) \), where these must satisfy the private information and limited commitment constraints, and where the continuation value must itself be drawn from the set of continuation values \([V(b(\theta)), \overline{V}(b(\theta))]\) that satisfy the private information and limited commitment constraints. Let \( \omega \) be the level of resources associated with initial debt \( b_{-1} \) at date 0. Then the best equilibrium for society, which maximizes social welfare at date 0, corresponds to the solution to the following program:

\[
\overline{V}(b_{-1}) = \max_{(b(\theta), V(b(\theta)))} \mathbb{E}[\theta U(\omega + b(\theta)) + \delta V(b(\theta))]
\]

subject to

\[
\alpha \theta U(\omega + b(\theta)) + \delta V(b(\theta)) \geq \alpha \theta U(\omega + b(\theta')) + \delta V(b(\theta')) \quad \text{for all } \theta, \theta' \in \Theta \tag{7}
\]

\[
\alpha \theta U(\omega + b(\theta)) + \delta V(b(\theta)) \geq \alpha \theta U(\omega + b^{p}(\omega, \theta)) + \delta V(b^{p}(\omega, \theta)) \quad \text{for all } \theta \in \Theta \tag{8}
\]

\[
b(\theta) \in [b(b_{-1}), \overline{b}(b_{-1})] \text{ and } V(b(\theta)) \in [\underline{V}(b(\theta)), \overline{V}(b(\theta))] \quad \text{for all } \theta \in \Theta. \tag{9}
\]

Constraints (7) and (8) are the private information and limited commitment constraints, analogous to (3) and (6), with \( b^{p}(\omega, \theta) \) denoting the government’s flexible borrowing level conditional on the lowest continuation value, analogous to (5):

\[
b^{p}(\omega, \theta) \in \arg \max_{b \in [b(b_{-1}), \overline{b}(b_{-1})]} \{\alpha \theta U(\omega + b) + \delta V(b)\}.
\]

Constraint (9) is the feasibility constraint, requiring that the government’s debt be within the specified bounds, and that continuation values be drawn from the set of equilibrium values. We assume that the solution to program \((P_{\text{max}})\) admits a piecewise continuously differentiable function \( b(\theta) \), which allows us to establish our results using perturbations.\(^\text{12}\)

Given the continuation value set \([\underline{V}(b(\theta)), \overline{V}(b(\theta))]\) and the characterization of equilibria that we will derive, it is also useful to write down the program that yields

\(^{12}\text{If the program admits multiple solutions that differ only on a countable set of types, we select the solution that maximizes social welfare for those types.}\)
the lowest value for society given initial debt $b_{-1}$:

$$V(b_{-1}) = \min_{(b(\theta), V(b(\theta)))} \mathbb{E} \left[ \theta U(\omega + b(\theta)) + \delta V(b(\theta)) \right] \quad (P_{\text{min}})$$

subject to (7), (8), and (9).

We make the following assumption:

**Assumption 1.** Parameters are such that $V(\cdot)$ and $\overline{V}(\cdot)$ are continuously differentiable and concave and satisfy $V(b) > \overline{V}(b)$ for all finite $b < \tau/(R - 1)$.

The first part, on the differentiability and concavity of the value functions, is guaranteed to hold for example if preferences $U(\cdot)$ satisfy either constant absolute risk aversion (CARA) or constant relative risk aversion (CRRA). The second part of Assumption 1 says that the equilibrium set is not a singleton. Section 5 provides necessary and sufficient conditions on parameters for this to hold in a setting with $U(\cdot) = \log(\cdot)$.

### 3 Benchmarks

To understand the role of governments’ deficit bias and private information, it is useful to consider what would happen in the absence of either of these frictions. Suppose first that governments are not biased towards current spending and thus $\alpha = 1$. Then trivially the best equilibrium for society has each government choosing the first-best policy, namely the policy that maximizes social welfare in each period. The governments’ private information plays no role absent a deficit bias, and social welfare is always at its first-best level.

Suppose next that $\alpha > 1$ but fiscal shocks are publicly observable and thus the private information constraint (7) in program $(P_{\text{max}})$ can be ignored. Then we can show that the best equilibrium for society prescribes either the first-best policy if the limited commitment constraint (8) does not bind, or the lowest enforceable level of debt conditional on the realized shock if (8) binds. In either case, the equilibrium prescribes the highest feasible continuation value for all shocks, implying that social welfare is at its highest feasible level $\overline{V}(\cdot)$ at all dates.

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13Details provided upon request.
Lemma 1. If $\alpha = 1$ or $\theta$ is observable, then $V_{t+1}(h^{t-1}, b_t) = \overline{V}(b_t)$ at every on-path history $h^t$ in the best equilibrium.

The takeaway is that neither of these benchmark settings can explain the presence of fiscal policy regimes. Since the best equilibrium restarts at each date, fiscal policy (conditional on debt) is independent of the history when governments have either no deficit bias or no private information.

4 Fiscal Policy Regimes

We now study the best equilibrium for society subject to the governments’ deficit bias and private information, which corresponds to the solution to program ($P_{\max}$). Subsection 4.1 presents some preliminaries. Subsection 4.2 shows that the best equilibrium is characterized by two regimes. Subsection 4.3 and Subsection 4.4 examine the form that fiscal policy takes in each of the two regimes, and Subsection 4.5 discusses transitions between the regimes.

4.1 Preliminaries

We provide some preliminaries that allow us to rewrite social welfare in a convenient way. The next lemma follows from standard arguments; see Fudenberg and Tirole (1991):

Lemma 2. $(b(\theta), V(b(\theta)))$ satisfies the private information constraint (7) if and only if $b(\theta)$ is nondecreasing and the following local private information constraints are satisfied:

1. At any point $\theta$ at which $b(\cdot)$, and thus $V(\cdot)$, are differentiable,

$$\frac{db(\theta)}{d\theta} (\alpha \theta U'(\omega + b(\theta)) + \delta V'(b(\theta))) = 0.$$

2. At any point $\theta$ at which $b(\cdot)$ is not differentiable,

$$\lim_{\theta' \uparrow \theta} \{\alpha \theta U'(\omega + b(\theta')) + \delta V(b(\theta'))\} = \lim_{\theta' \downarrow \theta} \{\alpha \theta U'(\omega + b(\theta')) + \delta V(b(\theta'))\}.$$
Observe that since \( b(\theta) \) is nondecreasing, satisfaction of (7) requires that \( V(b(\theta)) \) be nonincreasing in \( \theta \). The local private information constraints imply that the derivative of government welfare with respect to \( \theta \) is \( \alpha U(\omega + b(\theta)) \). Hence, in an equilibrium, government welfare for type \( \theta \in \Theta \) satisfies

\[
\alpha \theta U(\omega + b(\theta)) + \delta V(b(\theta)) = \alpha \theta U(\omega + b(\bar{\theta})) + \delta(V(b(\bar{\theta}))) + \int_{\bar{\theta}}^{\theta} \alpha U(\omega + b(\bar{\theta})) d\bar{\theta}. \tag{10}
\]

Following Amador, Werning, and Angeletos (2006), we can substitute (10) into the objective in \( (P_{\text{max}}) \) to rewrite social welfare as

\[
\alpha \theta U(\omega + b(\bar{\theta})) + \delta V(b(\bar{\theta})) + \alpha \int_{\bar{\theta}}^{\theta} U(\omega + b(\theta)) Q(\theta) d\theta, \tag{11}
\]

where

\[
Q(\theta) \equiv 1 - F(\theta) - \theta f(\theta)(1 - 1/\alpha).
\]

\( Q(\theta) \) represents the social value of increasing the level of borrowing prescribed for a government type \( \theta \). To interpret it, observe that the first term, \( 1 - F(\theta) \), resembles that in a virtual surplus formulation in mechanism design (Myerson, 1981).\(^{14}\) This term captures the fact that increasing the borrowing prescribed for a government type \( \theta \) requires increasing the borrowing prescribed for types higher than \( \theta \), so that their welfare increases at the same rate as required by the private information constraint (see (10)). The second term in \( Q(\theta) \) reflects the fact that, given the deficit bias \( \alpha > 1 \), society and the government disagree on the value of current borrowing. Prescribing more borrowing for a government type \( \theta \) reduces social welfare relative to government welfare by \( -\theta f(\theta)(1 - 1/\alpha) \), where \( \theta f(\theta) \) is the weight that social welfare places on the current utility from borrowing by type \( \theta \), and \( (1 - 1/\alpha) \) is the extent of the disagreement between society and the government.

The formulation above will be useful for our characterization of the best equilibrium in the next sections, which will appeal to properties of the function \( Q(\theta) \).

---

\(^{14}\)Similar to the standard virtual surplus expression, we can rewrite (11) using the inverse hazard rate:

\[
\alpha \theta U(\omega + b(\bar{\theta})) + \delta V(b(\bar{\theta})) + \alpha \int_{\bar{\theta}}^{\theta} U(\omega + b(\theta)) \left[ \frac{1 - F(\theta)}{f(\theta)} - \theta \left( 1 - \frac{1}{\alpha} \right) \right] f(\theta) d\theta.
\]
4.2 Two Regimes

We show that at any history in the best equilibrium, social welfare is either at its highest or lowest feasible level.

**Proposition 1.** Assume $Q'(\theta) \neq 0$ a.e., and suppose $b_t \in (b(b_{t-1}), \bar{b}(b_{t-1}))$ at all on-path histories $h^t$ in the best equilibrium. Then $V_{t+1}(h^{t-1}, b_t) \in \{V(b_t), \bar{V}(b_t)\}$ at every such history.

To prove this result, we first consider program $(P_{\text{max}})$ which yields the highest feasible welfare $V(b_{t-1})$ given initial debt $b_{t-1}$. We show that if $(b(\theta), V(b(\theta)))$ is a solution to this program with $b(\theta) \in (b(b_{t-1}), \bar{b}(b_{t-1}))$ for all $\theta$, then the prescribed continuation values satisfy $V(b(\theta)) \in \{V'(b(\theta)), \bar{V}(b(\theta))\}$ for all $\theta$. The proof uses perturbation arguments developed in Halac and Yared (2022). For intuition, recall that $Q(\theta)$ represents the weight that society assigns to prescribing more borrowing for a government type $\theta$. The condition in Proposition 1 says that the set of types $\theta$ for which $Q'(\theta) = 0$ is nowhere dense,\textsuperscript{15} which implies that $Q(\theta)$ is either strictly decreasing or strictly increasing over any sufficiently small interval. Since society then prefers to concentrate borrowing on either lower or higher government types in the interval, we show that a perturbation that spreads out incentives allows to increase welfare whenever $V(b(\theta)) \in (V'(b(\theta)), \bar{V}(b(\theta)))$ for some type $\theta$.

Given the solution to $(P_{\text{max}})$, we then consider program $(P_{\text{min}})$ which yields the lowest feasible welfare $\bar{V}(b_{t-1})$ given initial debt $b_{t-1}$. We show that analogous perturbation arguments apply to this program; essentially, any perturbation that increases welfare when $Q(\theta)$ is increasing (decreasing) then reduces welfare when $Q(\theta)$ is decreasing (increasing). Hence, we obtain that if $(b(\theta), V(b(\theta)))$ is a solution to $(P_{\text{min}})$ with $b(\theta) \in (b(b_{t-1}), \bar{b}(b_{t-1}))$ for all $\theta$, then $V(b(\theta)) \in \{\underline{V}(b(\theta)), \bar{V}(b(\theta))\}$ for all $\theta$. Moreover, since the results for $(P_{\text{max}})$ and $(P_{\text{min}})$ hold for any finite $b_{t-1} < \tau/(R - 1)$, it follows that if debt is interior at all on-path histories, then continuation values only travel to the extreme points of the feasible set in the best equilibrium. Note that this property is necessary for the maximization of social welfare at time 0: Proposition 1 says that any equilibrium with interior continuation values is strictly dominated.

The implication of Proposition 1 is that fiscal policy is characterized by two regimes. At any point in the best equilibrium, governments are either in a regime that

\textsuperscript{15}Given $f(\theta)$ continuously differentiable, this condition holds generically. Specifically, this condition fails only if $\theta f'(\theta)/f(\theta) = -(2 - 1/\alpha)/(1 - 1/\alpha)$ for a positive mass of types $\theta$, but then any arbitrarily small perturbation of $\alpha$ would render the condition true.
maximizes social welfare—which, for reasons that will become evident, we will call the *fiscally responsible regime*—or in a regime that minimizes social welfare—which we will call the *fiscally irresponsible regime*. Since $\overline{V}(\cdot) > \underline{V}(\cdot)$ by Assumption 1, the policies in each regime are distinct from each other. Thus, if both regimes occur on path in the best equilibrium, then fiscal policy features history dependence: conditional on debt, the policy that is implemented at a given date depends on whether the economy is in the fiscally responsible or fiscally irresponsible regime.

There are a number of questions that Proposition 1 raises. First, what form does fiscal policy take in each of the two regimes? Second, what triggers a transition from one regime to the other? And finally, can regime transitions occur on path in the best equilibrium? We address the first two questions in Subsection 4.3–Subsection 4.5 and the last question in Section 5. To facilitate our analysis, we maintain the following assumption for the rest of the paper:

**Assumption 2.** There is $\hat{\theta} \in \Theta$ such that $Q'(\theta) < 0$ if $\theta < \hat{\theta}$ and $Q'(\theta) > 0$ if $\theta > \hat{\theta}$.

This assumption says that for $\theta < \hat{\theta}$, society prefers to concentrate borrowing on relatively low government types, whereas for $\theta > \hat{\theta}$, society prefers to concentrate borrowing on relatively high government types. Note that the assumption allows for $Q(\theta)$ to be strictly decreasing or strictly increasing over the whole set $\Theta$; in this case, $\hat{\theta}$ is defined as either the upper bound or the lower bound of the set. Assumption 2 holds for a broad range of distribution functions, including uniform, exponential, log-normal, gamma, and beta for a subset of its parameters, and is analogous to assumptions used in Amador, Werning, and Angeletos (2006) and Halac and Yared (2022).

### 4.3 Fiscal Responsibility

We study fiscal policy in the fiscally responsible regime by characterizing the solution to program $(P_{\text{max}})$. Given resources $\omega$ associated with initial debt $b_{-1}$, let us first define $b^r(\omega, \theta)$ as the government’s flexible borrowing level conditional on the highest continuation value:

$$b^r(\omega, \theta) \in \arg \max_{b \in [b(b_{-1}), \overline{b}(b_{-1})]} \{\alpha \theta U(\omega + b) + \delta \overline{V}(b)\}.$$ 

Using this object, we next define a *maximally enforced deficit limit*:
Definition 1. \((b(\theta), V(b(\theta)))\) is a maximally enforced deficit limit if there exist \(\theta^* \in [0, \theta)\) and finite \(\theta^{**} > \max\{\theta^*, \theta\}\) such that

\[
\{b(\theta), V(b(\theta))\} = \begin{cases} 
\{b^r(\omega, \theta), V(b^r(\omega, \theta))\} & \text{if } \theta < \theta^* \\
\{b^r(\omega, \theta^*), V(b^r(\omega, \theta^*))\} & \text{if } \theta \in [\theta^*, \theta^{**}] \\
\{b^p(\omega, \theta), V(b^p(\omega, \theta))\} & \text{if } \theta > \theta^{**}
\end{cases}
\]  

where

\[
\alpha \theta^{**} U(\omega + b^r(\omega, \theta^*)) + \delta V(b^r(\omega, \theta^*)) = \alpha \theta^{**} U(\omega + b^p(\omega, \theta^{**})) + \delta V(b^p(\omega, \theta^{**})).
\]

Under a maximally enforced deficit limit, each government of type \(\theta \in [\theta, \theta^*)\) chooses its flexible debt level conditional on the highest continuation value, \(b^r(\omega, \theta)\); each government of type \(\theta \in [\theta^*, \theta^{**}]\) chooses type \(\theta^{**}\)'s flexible debt level conditional on the highest continuation value, \(b^r(\omega, \theta^{**})\); and each government of type \(\theta \in (\theta^{**}, \theta]\) chooses its flexible debt level conditional on the lowest continuation value, \(b^p(\omega, \theta)\). Governments of type \(\theta \leq \theta^{**}\) receive the highest continuation value \(V(b(\theta))\) and governments of type \(\theta > \theta^{**}\) the lowest continuation value \(V(b(\theta))\). By (13), the limited commitment constraint holds with equality when a government's type is \(\theta^{**}\), and one can verify (see Lemma 5 in Appendix A) that this constraint and the private information constraint are satisfied for all government types.

We obtain the following result:

Proposition 2. If \((b(\theta), V(b(\theta)))\) is a solution to \((P_{\text{max}})\) with \(b(\theta) \in (\underline{b}(b_{-1}), \overline{b}(b_{-1}))\) for all \(\theta \in \Theta\), then it satisfies (12)-(13) for some \(\theta^* \in [0, \theta)\) and finite \(\theta^{**} > \max\{\theta^*, \theta\}\). Hence, under any interior solution, the fiscally responsible regime takes the form of a maximally enforced deficit limit.

Given initial debt \(b_{-1}\), the fiscally responsible regime yielding value \(V(b_{-1})\) is characterized by a maximally enforced deficit limit, where this limit is associated with the borrowing level \(b^r(\omega, \theta^*)\). If a government respects the limit, it is rewarded with a continuation in the fiscally responsible regime which yields the highest feasible continuation value. If a government instead breaches the limit, it is punished with a transition to the fiscally irresponsible regime which yields the lowest feasible continuation value. These rewards and punishments provide governments with incentives to limit their borrowing, hence our term of fiscal responsibility.
To describe the proof of this result, recall from Proposition 1 that any (interior) solution to program \( \mathcal{P}_{\text{max}} \) prescribes a continuation value \( V(b(\theta)) \) equal to either \( \overline{V}(b(\theta)) \) or \( \underline{V}(b(\theta)) \). We show that under Assumption 2, the prescribed continuation values are monotonic, with either all government types receiving the highest continuation value conditional on debt, or only types above an interior point \( \theta^{**} \) being punished with the lowest continuation value conditional on debt. We further establish that the prescribed debt \( b(\theta) \) is continuous for all \( \theta \leq \theta^{**} \), and therefore that the solution must take the form of a maximally enforced deficit limit.

Proposition 2 tells us that at any point in the best equilibrium, fiscal policy can take one of two forms. One possible form is a maximally enforced deficit limit specifying \( \theta^{**} \geq \overline{\theta} \). In this case, the government respects the deficit limit—that is, it chooses a debt level below the threshold \( b^r(\omega, \theta^{**}) \)—under all shocks, so the economy remains in the fiscally responsible regime associated with welfare \( \overline{V}(\cdot) \) in the following period. The other possible form is a maximally enforced deficit limit specifying \( \theta^{**} < \overline{\theta} \). In this case, the government breaks the deficit limit—that is, it chooses a debt level above the threshold \( b^r(\omega, \theta^{**}) \)—under high enough shocks. The economy remains in the fiscally responsible regime associated with welfare \( \overline{V}(\cdot) \) if the realized shock satisfies \( \theta \leq \theta^{**} \); if instead a shock \( \theta > \theta^{**} \) is realized, the economy transitions to the fiscally irresponsible regime associated with welfare \( \overline{V}(\cdot) \) in the following period.

### 4.4 Fiscal Irresponsibility

We study fiscal policy in the fiscally irresponsible regime by characterizing the solution to program \( \mathcal{P}_{\text{min}} \). We first define a maximally enforced surplus limit:

**Definition 2.** \((b(\theta), V(b(\theta)))\) is a maximally enforced surplus limit if there exist finite \( \theta^*_n > \overline{\theta} \) and \( \theta^{**}_n \in [\overline{\theta}, \min\{\theta^*_n, \overline{\theta}\}] \) such that

\[
\{b(\theta), V(b(\theta))\} = \begin{cases} 
\{b^r(\omega, \theta), \overline{V}(b^r(\omega, \theta))\} & \text{if } \theta > \theta^*_n \\
\{b^r(\omega, \theta^*_n), \overline{V}(b^r(\omega, \theta^*_n))\} & \text{if } \theta \in [\theta^*_n, \theta^*]
\end{cases}
\]

(14)

where

\[
\alpha \theta^{**}_n U(\omega + b^r(\omega, \theta^*_n)) + \delta \overline{V}(b^r(\omega, \theta^*_n)) = \alpha \theta^{**}_n U(\omega + b^p(\omega, \theta^{**}_n)) + \delta \overline{V}(b^p(\omega, \theta^{**}_n)).
\]

(15)
Under a maximally enforced surplus limit, each government of type $\theta \in (\theta^*_n, \bar{\theta}]$ chooses its flexible debt level conditional on the highest continuation value, $b'(\omega, \theta)$; each government of type $\theta \in [\theta^*_n, \theta^*_n]$ chooses type $\theta^*_n$’s flexible debt level conditional on the highest continuation value, $b'(\omega, \theta^*_n)$; and each government of type $\theta \in [\theta, \theta^{**}_n)$ chooses its flexible debt level conditional on the lowest continuation value, $b_p(\omega, \theta)$.

Governments of type $\theta \geq \theta^{**}_n$ receive the highest continuation value $V(b(\theta))$ and governments of type $\theta < \theta^{**}_n$ the lowest continuation value $V(b(\theta))$. By (15), the limited commitment constraint holds with equality when a government’s type is $\theta^{**}_n$, and one can verify that this constraint and the private information constraint are satisfied for all government types.

We obtain the following result:

**Proposition 3.** If $(b(\theta), V(b(\theta)))$ is a solution to $(P_{\text{min}})$ with $b(\theta) \in (\bar{b}(b_{-1}), \bar{b}(b_{-1}))$ for all $\theta \in \Theta$, then it satisfies (14)-(15) for some finite $\theta^*_n \geq \theta$ and $\theta^{**}_n \in [\theta, \min\{\theta^*_n, \bar{\theta}\})$. Hence, under any interior solution, the fiscally irresponsible regime takes the form of a maximally enforced surplus limit.

Given initial debt $b_{-1}$, the fiscally irresponsible regime yielding value $V(b_{-1})$ is characterized by a maximally enforced surplus limit, where this limit is associated with the borrowing level $b'(\omega, \theta^*_n)$. If a government respects the limit, it is rewarded with a transition to the fiscally responsible regime which yields the highest feasible continuation value. If a government instead breaches the limit, it is punished with a continuation in the fiscally irresponsible regime which yields the lowest feasible continuation value. These rewards and punishments provide governments with incentives to increase their borrowing, hence our term of fiscal irresponsibility.

To see why inducing overborrowing minimizes social welfare, take a government of type $\theta$. There are two ways in which the social welfare derived from this government can be made inefficiently low: either by inducing the government to borrow too little or by inducing it to borrow too much. Since governments are biased towards overborrowing, the latter option relaxes the limited commitment constraint and is a more efficient means of reducing welfare. Thus, in the fiscally irresponsible regime, all government types borrow above the socially optimal level; in fact, they all borrow weakly above, and some strictly above, their own preferred level.

Importantly, observe that the fiscally irresponsible regime is always temporary. This follows from the fact that the maximally enforced surplus limit described in Proposition 3 specifies $\theta^{**}_n < \bar{\theta}$. Hence, governments respect the surplus limit for all
shocks $\theta \in [\theta^*_n, \overline{\theta}]$, implying that the best equilibrium transitions back to the fiscally responsible regime with strictly positive probability.

The proof of Proposition 3 uses analogous arguments as that of Proposition 2. One step in the proof that requires additional care is establishing that the maximally enforced surplus limit indeed specifies $\theta^*_n < \overline{\theta}$. We prove that a surplus limit that is respected by government types $\theta \in [\theta^*_n, \overline{\theta}]$, for $\theta^*_n < \overline{\theta}$, achieves lower social welfare than an absorbing state in which a continuation value $V(\cdot)$ is sustained at all dates, with all government types choosing their flexible borrowing level conditional on such continuation value, $b^p(\omega, \theta)$. Intuitively, the social cost of increasing overborrowing outweighs the benefit of increasing the continuation value for high enough government types.

4.5 Regime Transitions

The results in Proposition 1-Proposition 3 have implications for the dynamics of debt. Starting in a fiscally responsible regime at date $t$, the best equilibrium takes the form of a maximally enforced deficit limit, which aims to counteract the governments’ deficit bias and limit overborrowing. If a shock $\theta_t \leq \theta^*$ is realized, the government at date $t$ respects the deficit limit and the equilibrium restarts in the fiscally responsible regime at $t + 1$. If instead $\theta_t > \theta^*$, the government at date $t$ breaks the deficit limit and the equilibrium transitions to the fiscally irresponsible regime at $t + 1$.

Starting in a fiscally irresponsible regime at date $t$, the best equilibrium takes the form of a maximally enforced surplus limit, which induces governments to succumb to their deficit bias and overborrow. If a shock $\theta_t \geq \theta^*_n$ is realized, the government at date $t$ respects the surplus limit and the equilibrium transitions to the fiscally responsible regime at $t + 1$. If instead $\theta_t < \theta^*_n$, the government at date $t$ breaks the surplus limit and the equilibrium restarts in the fiscally irresponsible regime at $t + 1$.

The characterization sheds light on the empirical path of fiscal policy discussed in the Introduction. Periods of fiscal consolidation can be understood as fiscally responsible behavior by governments which realize that deviating from such behavior would set a precedent for deviations by subsequent governments. As such, periods of fiscal consolidation end when shocks are sufficiently severe that the cost of setting this negative precedent is outweighed by the benefit of responding to current economic conditions. Analogously, periods of debt buildup can be understood as fiscally irresponsible behavior by governments which derive benefits from current spending...
and realize that future fiscal consolidations will occur once deficits become sufficiently large. As such, periods of debt buildup end when shocks are severe enough to demand such large deficits.

These dynamics provide an explanation for the persistence of fiscal policy at intermediate frequencies. Governments’ borrowing choices depend not only on current economic conditions and their inherited level of debt, but also on the regime in which they find themselves. Consistent with the evidence, and despite shocks being i.i.d., we thus find that fiscal policy (conditional on debt) is history-dependent and cannot be explained by contemporaneous variables alone. Moreover, persistent changes in fiscal policy are punctuated by crisis periods, as transitions between regimes occur when shocks to the value of spending are sufficiently high.

5 Analytical Example

Our results in Proposition 1-Proposition 3 hold under Assumption 1, which guarantees that the value functions are continuously differentiable and concave with $V(\cdot) > V(\cdot)$. Moreover, these results characterize the best equilibrium under interior solutions for debt. In this section, we describe an analytical example in which Assumption 1 holds and in which debt is interior along the equilibrium path, so that Proposition 1-Proposition 3 hold in all periods. Applying a factorization algorithm, we show that $V(\cdot) > V(\cdot)$ if and only if the governments’ deficit bias $\alpha$ is large enough. This means that governments must be sufficiently biased towards present spending for the equilibrium to feature fiscal policy regimes.

5.1 Primitives and Preliminaries

Take a utility of government spending $U(\cdot) = \log(\cdot)$. Let $s_t \in [0, 1]$ denote the saving rate at time $t$, defined as the fraction of lifetime resources that are not spent at $t$:

$$g_t = (1-s_t)R \left( \frac{\tau}{R-1} - b_{t-1} \right).$$

Then social welfare at date $t$ can be written as

$$V_t = \mathbb{E}_t \left[ \sum_{k=0}^{\infty} \delta^k \left( \theta_{t+k}U(1-s_{t+k}) + \frac{\delta}{1-\delta}\theta_{t+k}U(s_{t+k}) \right) \right] + \chi(b_{t-1}), \quad (16)$$
where $\chi(b_{t-1})$ is a constant that depends on $b_{t-1}$.

Observe that under this parameterization, a choice of debt $b_t$ is equivalent to a choice of saving rate $s_t$. Moreover, the bounds on feasible debt levels $[\underline{b}(b_{t-1}), \overline{b}(b_{t-1})]$ are replaced with bounds on saving rates $[\underline{s}, \overline{s}]$, where $\underline{s} > 0$ and $\overline{s} < 1$.

The representation in (16) has two main implications. The first implication is that welfare is separable in the inherited level of debt. This separability means that the continuation equilibria characterizing the highest and lowest feasible continuation values, $\overline{V}(b)$ and $\underline{V}(b)$, admit future sequences of saving rates that are independent of initial debt. Using (16), we can then show (see Appendix B) that these values are continuously differentiable and concave, and that they satisfy

$$\overline{V}(b) - \underline{V}(b) = P^*$$

for any initial debt $b$ and some $P^* \geq 0$ that is independent of $b$.

The second implication of the representation in (16) is that the solutions to $(P_{\text{max}})$ and $(P_{\text{min}})$ prescribe levels of debt that are interior. This follows from the fact that, given log preferences, $\lim_{s \to 0} U(s) = \lim_{s \to 1} U(1 - s) = -\infty$. Hence, for sufficiently wide bounds $[\underline{s}, \overline{s}]$, we obtain $s_t \in (\underline{s}, \overline{s})$ and thus $b_t \in (\underline{b}(b_{t-1}), \overline{b}(b_{t-1}))$ at all dates $t$ in any equilibrium.

These properties of the value functions and of the solutions to $(P_{\text{max}})$ and $(P_{\text{min}})$ imply that, if $\overline{V}(b) > \underline{V}(b)$ for all finite $b < \tau/(R - 1)$, then Assumption 1 holds and the characterization in Proposition 1-Proposition 3 applies to this environment. In fact, note that since programs $(P_{\text{max}})$ and $(P_{\text{min}})$ can be represented as independent of debt with a choice of saving rate $s(\theta)$ for each government type $\theta$, in this case the characterization yields maximally enforced deficit and surplus limits with thresholds $\{\theta^*, \theta^{**}\}$ and $\{\theta^*_n, \theta^{**}_n\}$ that are also independent of initial debt. We are thus simply left to consider the conditions under which $\overline{V}(b) > \underline{V}(b)$, or, equivalently by (17), the conditions under which $P^* > 0$.

To facilitate the analysis, we will take our environment to have a distribution of shocks satisfying $f(\bar{\theta}) = f(\tilde{\theta}) = 0$. This implies $Q(\tilde{\theta}) = 1$ and $Q(\bar{\theta}) = 0$; that is, the social value of increasing a government’s prescribed borrowing level is zero for the boundary types.

\footnote{This constant is equal to $E_t \sum_{k=0}^{\infty} \delta^k \theta_{t+k} U(R^{k+1}\tau/(R - 1) - R^{k+1}b_{t-1})$.}

\footnote{Note that the analog of this assumption would hold over an unbounded support, since in that circumstance $\lim_{\theta \to 0} Q(\theta) = 1$ and $\lim_{\theta \to \infty} Q(\theta) = 0$.} Since $Q(\theta)$ equals 1 for $\theta < \bar{\theta}$ and 0 for $\theta > \bar{\theta}$, this distributional
assumption ensures that $Q(\theta)$ is continuous at $\theta$ and $\bar{\theta}$. This in turn implies that under maximally enforced deficit and surplus limits as defined in Definition 1 and Definition 2, social welfare is everywhere differentiable with respect to the thresholds $\{\theta^*, \theta^{**}, \theta^n, \theta^{**n}\}$. Moreover, for $\alpha > 1$ and $\hat{\theta}$ defined in Assumption 2, we obtain $\hat{\theta} \in (\bar{\theta}, \theta)$.

5.2 Factorization Algorithm

We develop a factorization algorithm to characterize equilibrium behavior in this analytical example. Observe that by (17), we can define a government’s flexible level of borrowing given resources $\omega$ and shock $\theta$ by $b^f(\theta) \equiv b^r(\omega, \theta) = b^p(\omega, \theta)$, independently of the value of $P^*$. Let $g^f(\theta) \equiv b^f(\theta) + \omega$ denote the corresponding flexible level of spending, where we omit the dependence on $\omega$ to reduce notation. We consider a candidate interior equilibrium with fiscal regimes given by maximally enforced deficit and surplus limits as defined in Definition 1 and Definition 2, parameterized by the thresholds $\{\theta^*, \theta^{**}, \theta^n, \theta^{**n}\}$. This equilibrium can be represented by a system of equations. Specifically, we show in Appendix B that integrating conditions (13) and (15) in Definition 1 and Definition 2 and substituting with (17) yields

\begin{align}
\delta P^* &= \alpha \int_{\theta^*}^{\theta^{**}} [U(g^f(\theta)) - U(g^f(\theta^*))] d\theta, \quad (18) \\
\delta P^* &= \alpha \int_{\theta^n}^{\theta^{**n}} [U(g^f(\theta)) - U(g^f(\theta^n))] d\theta. \quad (19)
\end{align}

Moreover, writing the values $V(b)$ and $V(b)$ with the representation of welfare given in (11), computing the difference and again using (17), we obtain

\begin{align}
P^* = \delta P^* + \alpha \left[ \int_{\theta^*}^{\theta^{**}} (U(g^f(\theta^*)) - U(g^f(\theta))) Q(\theta) d\theta \
- \int_{\theta^n}^{\theta^{**n}} (U(g^f(\theta^*)) - U(g^f(\theta))) Q(\theta) d\theta \right]. \quad (20)
\end{align}

Equations (18) and (19) define the limited commitment constraints for a maximally enforced deficit limit in the fiscally responsible regime and for a maximally enforced surplus limit in the fiscally irresponsible regime, respectively. Equation (20) defines
the value of punishment. Using this representation, consider the following program:

\[
T(P) = \max_{\theta^*, \theta^{**}, \theta_n^*, \theta_n^{**}} \left\{ \delta P + \alpha \left[ \int_{\theta_n^*}^{\theta_n^{**}} (U(g^f(\theta_n^*))) - U(g^f(\theta)) \right] Q(\theta) d\theta \right. \\
\left. - \int_{\theta_n^*}^{\theta_n^{**}} (U(g^f(\theta_n^*))) - U(g^f(\theta)) \right] Q(\theta) d\theta \right\} \tag{21}
\]

subject to

\[
\delta P \geq \alpha \int_{\theta^*}^{\theta^{**}} [U(g^f(\theta)) - U(g^f(\theta^*))] d\theta \tag{22}
\]

\[
\delta P \geq \alpha \int_{\theta_n^*}^{\theta_n^{**}} [U(g^f(\theta_n^*))) - U(g^f(\theta)) \right] d\theta. \tag{23}
\]

We show in Appendix B that there exists a solution to this program that satisfies constraints (22)-(23) with equality. Moreover, we argue that the best equilibrium for society is unique and is characterized by the largest value of \( P^* \) that satisfies \( T(P^*) = P^* \). Intuitively, \( P \) represents the largest punishment that can be inflicted on a government conditional on its choice of spending. Given a level of punishment \( P \) that can be inflicted in the future, the program computes the largest punishment \( T(P) \) that can be inflicted in the present. A fixed point \( T(P) = P \) represents an equilibrium in which the largest punishment in the future supports the largest punishment in the present.

Figure 2 depicts the function \( T(P) \). We prove that \( T(P) \) is increasing and concave and satisfies \( T(0) = 0 \) and \( \lim_{P \to \infty} T'(P) < 1 \). The fact that \( T(0) = 0 \) is intuitive. The algorithm always admits a fixed point at 0 with \( \overline{V}(\cdot) = \underline{V}(\cdot) \) supported by governments choosing their flexible spending level \( g^f(\theta) \) at all dates. If the largest punishment that is inflicted in the future is zero, then the largest punishment that is inflicted in the present is also zero.

The fact that \( T(P) \) is concave with \( \lim_{P \to \infty} T'(P) < 1 \) means that \( T(P^*) = P^* \) for no more than a single point \( P^* > 0 \). There are two possible scenarios. The left panel of Figure 2 depicts a scenario in which \( T'(0) > 1 \) and thus there is a point \( P^* > 0 \) at which \( T(P) \) crosses the 45 degree line. In this case, \( \overline{V}(\cdot) > \underline{V}(\cdot) \), implying that Assumption 1 holds and therefore the best equilibrium admits fiscal regimes as described in Proposition 1-Proposition 3. The right panel of Figure 2 depicts the other scenario, in which \( T'(0) < 1 \) and thus \( T(P) \) never crosses the 45 degree line. In this case, the unique equilibrium has governments choosing their flexible spending
The left panel depicts a scenario in which $T'(0) > 1$, and the right panel in which $T'(0) < 1$.

Figure 2: Representation of the function $T(P)$. Level in all periods.

$T(P)$ is analogous to the factorization algorithm introduced in Abreu, Pearce, and Stacchetti (1990), but for our problem of adverse selection. The analog of $P$ in Abreu, Pearce, and Stacchetti (1990) would be the set of continuation values for the players, and their work characterizes those continuation values as a fixed point of their factorization algorithm. In our environment, which features a single player in any given period, the set of continuation values is a one-dimensional set. Hence, for our purposes, it is sufficient to consider the value of $P$, which is the difference between the highest and the lowest continuation values, $\nabla(b) - \nabla(b)$.

Another difference with Abreu, Pearce, and Stacchetti (1990) is how we will apply the factorization algorithm. In their setting, one starts with the largest set of continuation values and the algorithm is applied repeatedly to obtain the largest fixed point. However, beyond computing a fixed point, our concern is whether there is a fixed point that features regimes (i.e., a non-Markov equilibrium). Given our characterization of $T(P)$, we are able to obtain a condition for such a fixed point by applying the algorithm from below. Starting from the equilibrium with $P = 0$ in which all governments choose flexible spending (i.e., the Markov equilibrium in which governments “play Nash”), we obtain a sufficient condition for the factorization algorithm to converge to another fixed point when $P$ is raised above 0. We show that such a higher fixed point, if it exists, must be the unique best equilibrium. These results are presented in Proposition 4 below.
5.3 Conditions for Fiscal Policy Regimes

Proposition 4. Consider a setting with \( U(\cdot) = \log(\cdot), \) \( f(\theta) = f(\bar{\theta}) = 0, \) and bounds \( 0 < \bar{s} < \bar{s} < 1 \) on saving rates, with \( [\bar{s}, \bar{s}] \) sufficiently wide. There exist \( \tilde{\delta} \in (0, 1) \) and \( \tilde{\alpha} \in (1, \infty) \) such that if \( \delta > \tilde{\delta}, \) then \( V(\cdot) > V(\cdot) \) if and only if \( \alpha > \tilde{\alpha}. \) If \( \delta \leq \tilde{\delta}, \) then \( V(\cdot) = V(\cdot) \) for all \( \alpha \geq 1. \)

This proposition states that a pre-condition for the existence of fiscal regimes is that the discount factor \( \delta \) should be large enough. Governments must be sufficiently patient for the dynamic incentives provided by future play to deter them from choosing their flexible spending level \( g^f(\theta) \) in the present. If the discount factor is too low, then the unique equilibrium consists of all governments choosing their flexible level of spending \( g^f(\theta) \) in all periods.

Given a sufficiently large discount factor, the more interesting part of Proposition 4 is that the existence of fiscal regimes also requires the governments’ deficit bias \( \alpha \) to be sufficiently large. Observe that if \( \alpha = 1, \) the unique equilibrium has all governments choosing their flexible spending level (which in this case also corresponds to the first-best spending level) and therefore \( P = V(\cdot) - V(\cdot) = 0. \) In other words, punishments are infeasible when \( \alpha = 1, \) since preferences are dynamically consistent across governments and future governments cannot credibly punish current ones. What Proposition 4 states is that for a small enough bias, it is also the case that \( P = 0. \) Dynamic incentives with \( P > 0 \) can be provided if and only if \( \alpha > \tilde{\alpha}. \)

The intuition for this result stems from the concavity of the value functions. For \( \alpha \) close to 1, the highest continuation value \( V(\cdot) \) is close to its first-best level. By concavity, this means that a small difference in continuation values between two regimes would require a large difference in spending. However, governments are not willing to choose a spending level that is far from first best when their deficit bias is small. Hence, strong enough future punishments cannot be credibly imposed as to provide dynamic incentives, and therefore the equilibrium continues to be uniquely given by all governments choosing their flexible spending level when \( \alpha \in (1, \tilde{\alpha}). \)

As \( \alpha \) increases above \( \tilde{\alpha}, \) two things happen. First, welfare moves away from first best, so concavity implies that a given difference in continuation values can be achieved with smaller differences in spending. Second, governments are more

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\(^{18}\)The proof of Proposition 4 provides an expression for the cutoff \( \tilde{\delta} \in (0, 1). \)

\(^{19}\)The proof of Proposition 4 shows that the cutoff \( \tilde{\alpha} \) is a decreasing function of \( \delta. \) That is, the higher is \( \delta > \tilde{\delta}, \) the larger is the range of biases \( \alpha \) under which the equilibrium admits fiscal regimes.
willing to spend above the first best level as they are more severely biased towards the present. Both of these effects imply that once $\alpha$ becomes large enough, strong future punishments can be credibly imposed to deter governments from choosing their flexible spending level.

We thus obtain that for $\delta > \tilde{\delta}$ and $\alpha > \tilde{\alpha}$, the best equilibrium for society is characterized by fiscally responsible and fiscally irresponsible regimes as described in Proposition 1–Proposition 3. Does the economy transition between the two regimes along the equilibrium path? The following corollary guarantees that the answer is yes for a range of values of the governments’ deficit bias.

**Corollary 1.** Take the setting of Proposition 4 with $\delta > \tilde{\delta}$. There exists $\tilde{\alpha} > \tilde{\alpha}$ such that if $\alpha \in (\tilde{\alpha}, \tilde{\tilde{\alpha}})$, then the best equilibrium features regime transitions on path.

Given an equilibrium with regimes, recall from Subsection 4.3 that whether or not regime transitions occur on path depends on the tightness of the maximally enforced deficit limit that is implemented in the fiscally responsible regime. Transitions do not occur if the deficit limit is lax enough that governments respect it under all shocks. Instead, if the deficit limit is tighter, the economy (temporarily) transitions to the fiscally irresponsible regime when high enough shocks are realized. Corollary 1 says that we must be in the latter scenario if $\alpha$ is sufficiently close to the cutoff $\tilde{\alpha}$. Intuitively, in this case, the punishment $P = \overline{V}(\cdot) - \underline{V}(\cdot)$ that can be sustained in equilibrium is only slightly above zero, so the deficit limit would have to be very lax for governments to be willing to always respect it. Since $f(\overline{\theta}) = 0$, it is socially beneficial to tighten the deficit limit to improve fiscal discipline, and to let the economy transition to the fiscally irresponsible regime following high enough shocks which are unlikely.

The results above are useful for understanding the evolution of government debt in the U.S. As described in the introduction and shown in Figure 1, U.S. public debt as a percentage of GDP followed a downward trajectory between World War II and 1970, while exhibiting transitions between persistent fiscal regimes between 1970 and 2020. Proposition 4 and Corollary 1 suggest that the difference between these two periods might be partly explained by governments’ deficit bias increasing in the latter period. In fact, the political economy literature argues that political biases have increased over the last decades as a result of demographic and political factors, and that higher biases have resulted in rising debt levels across advanced economies (see the papers cited in fn. 5). Our results indicate that increased biases may not only lead to higher
long-run debt growth, but also to the emergence of fiscal regimes punctuated by crisis periods.

6 Concluding Remarks

We have studied a political economy mechanism that explains the presence of persistent regimes in fiscal policy. An important insight from our analysis is that the same deficit bias that can lead governments to overaccumulate debt is also a force that can lead the economy to fluctuate between periods of fiscal responsibility and irresponsibility, with transitions occurring during crises when fiscal needs are large. These fluctuations emerge in our setting not because of fluctuations in power across heterogeneous governments, but because of the dynamic strategic interaction between identical governments with the same bias. We find that fiscal regimes emerge only if the governments’ bias is sufficiently large: the threat of fiscal irresponsibility in the future is then severe enough to sustain fiscal responsibility in the present.

We believe there are potentially interesting directions for future research. One possible extension is to study governments whose bias applies to multiple periods. While in our formulation the preferences of the government regarding future policies coincide with those of society, a government’s bias that extends to future periods would make the problem closer to one of repeated delegation. Another potential direction would be to consider a group of countries or subnational regions. The properties of fiscal policy in the different regions would depend on the nature of collective punishments that could be sustained in equilibrium.

Finally, while we have focused on fiscal policy, the insights of this paper may be applied to other settings. For example, consider an individual who suffers from a self-control problem and wishes to curb his consumption of a temptation good, such as television or alcohol, while at the same time responding to consumption shocks over time. Our results suggest that the best self-enforcing consumption plan takes the form of a consumption threshold. The individual may violate the threshold when his value of consumption is high enough, and violation is punished by future selves with temporary over-consumption. Moreover, transitions in and out of periods of self-enforcing binging occur only if the individual’s present bias is high enough.
References


A Proofs for Section 3 and Section 4

We introduce some terminology. When studying programs $(\mathcal{P}_{\text{max}})$ and $(\mathcal{P}_{\text{min}})$, we will say that an allocation $(b(\theta), V(b(\theta)))$ is incentive feasible if it satisfies constraints (7)-(9), and it is optimal if it is a solution to the program.

A.1 Proof of Lemma 1

Take first the case in which $\alpha = 1$. Then trivially the best equilibrium has each government choosing the first-best policy, and thus social welfare is at its first-best level at each history.

Take next the case in which $\theta$ is observable. Suppose by contradiction that there is an on-path history in the best equilibrium at which $V(b(\theta)) < V(b(\theta))$. Since increasing $V(b(\theta))$ relaxes the limited commitment constraint (8) (and since the private information constraint (7) can be ignored in this case), it follows that there is a perturbation that increases $V(b(\theta))$ that is feasible. Since such a perturbation increases the objective in $(\mathcal{P}_{\text{max}})$, we reach a contradiction.

A.2 Proof of Proposition 1

Assume $Q'(\theta) \neq 0$ a.e. We prove the proposition by establishing Lemma 3 and Lemma 4.

Lemma 3. If $(b(\theta), V(b(\theta)))$ is a solution to $(\mathcal{P}_{\text{max}})$ with $b(\theta) \in (b(b_{-1}), \bar{b}(b_{-1}))$ for all $\theta \in \Theta$, then $V(b(\theta)) \in \{\underline{V}(b(\theta)), \overline{V}(b(\theta))\}$ for all $\theta \in \Theta$. 

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Proof. Take any solution \((b(\theta), V(b(\theta)))\) to \((P_{\text{max}})\) with \(b(\theta) \in (b(b_{-1}), \overline{b}(b_{-1}))\) for all \(\theta \in \Theta\). We proceed in three steps.

**Step 1.** We show that \(V(b(\theta))\) is left-continuous at each \(\theta \in (\overline{\theta}, \overline{\theta}]\) and \(V(b(\theta)) = \overline{V}(b(\theta))\).

For the first claim, suppose by contradiction that there is \(\theta \in (\overline{\theta}, \overline{\theta}]\) at which \(V(b(\theta))\) is not left-continuous. Denote \((b(\theta - db), V(b(\theta - db))) \equiv \lim_{\theta' \uparrow \theta} (b(\theta'), V(b(\theta'))).\) By Lemma 2,

\[ 0 < \alpha \theta \left( U(\omega + b(\theta)) - U(\omega + b(\theta^-)) \right) = \delta \left( V(b(\theta^-)) - V(b(\theta)) \right). \]

Given \(\alpha > 1\), this implies

\[ \theta \left( U(\omega + b(\theta)) - U(\omega + b(\theta^-)) \right) < \delta \left( V(b(\theta^-)) - V(b(\theta)) \right). \]

It follows that a perturbation that assigns \((b(\theta^-), V(b(\theta^-)))\) to type \(\theta\) is incentive feasible, strictly increases social welfare from type \(\theta\), and does not affect social welfare from types other than \(\theta\). This contradicts the optimality of the original allocation, proving the claim.

For the second claim, suppose by contradiction that \(V(b(\theta)) < \overline{V}(b(\theta))\). We perform a perturbation where we change \(b(\theta) \in (\overline{b}, \overline{b})\) by \(-db(\theta) < 0\) arbitrarily close to zero and change \(V(b(\theta))\) so as to keep type \(\theta\) equally well off:

\[ db(\theta) \alpha \theta U'(\omega + b(\theta)) + \delta dV(b(\theta)) = 0. \]

This perturbation is incentive feasible and does not affect social welfare from types \(\theta \in (\overline{\theta}, \overline{\theta}]\). The change in social welfare from type \(\theta\) is equal to

\[ -[db(\theta) \alpha \theta U'(\omega + b(\theta)) + \delta dV(b(\theta))] = db(\theta) \alpha \theta U'(\omega + b(\theta)) (\alpha - 1) > 0. \]

This contradicts the optimality of the original allocation, proving the claim.

**Step 2.** We show that \(V(b(\theta))\) is a step function over any interval \([\theta^L, \theta^H]\) with \(V(b(\theta)) \in (\overline{V}(b(\theta)), \overline{V}(b(\theta)))\) for \(\theta \in [\theta^L, \theta^H]\).

By the private information constraints, \(V(b(\theta))\) is piecewise continuously differentiable and nonincreasing. Suppose by contradiction that there is an interval \([\theta^L, \theta^H]\)
over which \( V(b(\theta)) \) is continuously strictly decreasing in \( \theta \) with \( 0 < V(b(\theta)) < \overline{V}(b(\theta)) \). By Lemma 2, \( b(\theta) \) must be continuously strictly increasing over the interval, and without loss we can take an interval over which \( b(\theta) \) is continuously differentiable. Moreover, by the generic property that \( Q'(\theta) \neq 0 \) a.e., we can take an interval with either \( Q'(\theta) > 0 \) or \( Q'(\theta) < 0 \) for all \( \theta \in [\theta^L, \theta^H] \). We consider each possibility in turn.

**Case 1:** Suppose \( Q'(\theta) < 0 \) for all \( \theta \in [\theta^L, \theta^H] \). We show that there is an incentive feasible flattening perturbation that rotates the increasing borrowing schedule \( b(\theta) \) clockwise over \( [\theta^L, \theta^H] \) and strictly increases social welfare. Define

\[
\overline{U} = \frac{1}{(\theta^H - \theta^L)} \int_{\theta^L}^{\theta^H} U(\omega + b(\theta)) d\theta.
\]

For given \( \kappa \in [0, 1] \), let \( \tilde{b}(\theta, \kappa) \) be the solution to

\[
U(\omega + \tilde{b}(\theta, \kappa)) = \kappa \overline{U} + (1 - \kappa)U(\omega + b(\theta)), \quad (A.1)
\]

which clearly exists. Define \( \tilde{V}(\tilde{b}(\theta)) \) as the solution to

\[
\alpha \theta U(\omega + \tilde{b}(\theta, \kappa)) + \delta \tilde{V}(\tilde{b}(\theta, \kappa)) = \alpha \theta^L U(\omega + b(\theta^L)) + \delta V(b(\theta^L)) + \int_{\theta^L}^{\theta} \alpha U(\omega + \tilde{b}(\theta, \kappa)) d\tilde{\theta}. \quad (A.2)
\]

The original allocation corresponds to \( \kappa = 0 \). We consider a perturbation where we increase \( \kappa \) marginally above zero if and only if \( \theta \in [\theta^L, \theta^H] \). Note that differentiating (A.1) and (A.2) with respect to \( \kappa \) yields

\[
\frac{d\tilde{b}(\theta, \kappa)}{d\kappa} = \alpha \theta^L \frac{U' - U(\omega + b(\theta))}{U'^{(\omega + \tilde{b}(\theta, \kappa))}}, \quad (A.3)
\]

\[
\frac{d\tilde{b}(\theta, \kappa)}{d\kappa} (\alpha \theta U' + \delta \tilde{V}'(\tilde{b}(\theta, \kappa))) = \int_{\theta^L}^{\theta} \alpha U'(\omega + \tilde{b}(\theta, \kappa)) d\tilde{\theta}. \quad (A.4)
\]

Substituting (A.3) in (A.4) yields that for a type \( \theta \in [\theta^L, \theta^H] \), the change in government welfare from a marginal increase in \( \kappa \), starting from \( \kappa = 0 \), is equal to

\[
D(\theta) \equiv \int_{\theta^L}^{\theta} \alpha \left( \frac{U - U(\omega + b(\tilde{\theta}))}{\overline{U} - U(\omega + b(\theta))} \right) d\tilde{\theta}.
\]

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We begin by showing that the perturbation satisfies constraints (7)-(9). For (7), note that $D(\theta_L) = D(\theta_H) = 0$, so the perturbation leaves the government welfare of types $\theta_L$ and $\theta_H$ (and that of types $\theta < \theta_L$ and $\theta > \theta_H$) unchanged. Using Lemma 2 and the representation in (10), it then follows from (A.2) and the fact that $\tilde{b}(\theta, \kappa)$ is nondecreasing that the perturbation satisfies (7) for all $\theta \in \Theta$ and any $\kappa \in [0, 1]$. 

To prove that the perturbation satisfies (8), we show that the government welfare of types $\theta \in [\theta_L, \theta_H]$ weakly rises when $\kappa$ increases marginally. Since $D(\theta_L) = D(\theta_H) = 0$, it is sufficient to show that $D'(\theta)$ is concave over $(\theta_L, \theta_H)$ to prove that $D'(\theta) \geq 0$ for all $\theta$ in this interval. Indeed, we can verify that $D''(\theta) = -\alpha U'(\omega + b(\theta)) \frac{db(\theta)}{d\theta} < 0$.

Lastly, observe that (9) is satisfied for $\kappa > 0$ small enough. This follows from $V(b(\theta))$ being continuous and from $V(b(\theta)) \in (V(b(\theta)), \overline{V}(b(\theta)))$ for $\theta \in [\theta_L, \theta_H]$ in the original allocation.

We next show that the perturbation strictly increases social welfare. Using the representation in (11), the change in social welfare from an increase in $\kappa$ is equal to

$$\alpha \int_{\theta_L}^{\theta_H} \frac{\tilde{b}(\theta, \kappa)}{d\kappa} U'(\omega + \tilde{b}(\theta, \kappa))Q(\theta)d\theta.$$ 

Substituting with (A.3) yields that at $\kappa = 0$, this is equal to

$$\alpha \int_{\theta_L}^{\theta_H} (\overline{U} - U(\omega + b(\theta))) Q(\theta)d\theta.$$ 

This is an integral over the product of two terms. The first term is strictly decreasing in $\theta$ since $b(\theta)$ is strictly increasing over $[\theta_L, \theta_H]$. The second term is also strictly decreasing in $\theta$; this follows from $Q'(\theta) < 0$ for all $\theta \in [\theta_L, \theta_H]$. Therefore, the two terms are positively correlated with one another, and thus the change in social welfare is strictly greater than

$$\alpha \int_{\theta_L}^{\theta_H} (\overline{U} - U(\omega + b(\theta)))d\theta \int_{\theta_L}^{\theta_H} Q(\theta)d\theta,$$

which is equal to 0. Hence, we obtain that if $V(b(\theta))$ is strictly interior and $Q'(\theta) < 0$ over a given interval, then $V(b(\theta))$ must be a step function over the interval.

Case 2: Suppose $Q'(\theta) > 0$ for all $\theta \in [\theta_L, \theta_H]$. Recall that $b(\theta)$ is continuously strictly increasing over $[\theta_L, \theta_H]$. We begin by showing that the limited commitment constraint
cannot bind for all $\theta \in [\theta^L, \theta^H]$. Suppose by contradiction that it does. Using the representation of government welfare in (10), this implies
\[
\int_{\theta^L}^{\theta^H} \alpha(U(\omega + b(\omega, \bar{\theta})) - U(\omega + b(\bar{\theta})))d\bar{\theta} = 0
\]
for all $\theta \in [\theta^L, \theta^H]$, which requires $(b(\theta), V(b(\theta))) = (b^{\theta}(\omega, \theta), V(b(\omega, \theta)))$ for all $\theta \in (\theta^L, \theta^H)$. However, this contradicts the assumption that $V(b(\theta)) \in (V(b(\theta)), V(b(\theta)))$ for all $\theta \in [\theta^L, \theta^H]$. Hence, the limited commitment constraint cannot bind for all types in the interval, and without loss we can take an interval with this constraint being slack for all $\theta \in [\theta^L, \theta^H]$

We next show that there is a steepening perturbation that is incentive feasible and strictly increases social welfare. Consider drilling a hole around a type $\theta^M$ within $[\theta^L, \theta^H]$ so that we marginally remove the allocation around this type. That is, $\theta^M$ no longer choose $(b(\theta^M), V(b(\theta^M)))$ and is indifferent between jumping to the lower or upper limit of the hole. With some abuse of notation, denote the limits of the hole by $\theta^L$ and $\theta^H$, where the perturbation marginally increases $\theta^H$ from $\theta^M$. Since the limited commitment constraint is slack for all $\theta \in [\theta^L, \theta^H]$, the perturbation is incentive feasible. The change in social welfare is
\[
\alpha \int_{\theta^M}^{\theta^H} \frac{db(\theta^H)}{d\theta^H}U'(\omega + b(\theta^H))Q(\theta)d\theta + \alpha \frac{d\theta^M}{d\theta^H} \left(U(\omega + b(\theta^L)) - U(\omega + b(\theta^H))\right)Q(\theta^M).
\]
By indifference of type $\theta^M$,
\[
\alpha \theta^M U(\omega + b(\theta^L)) + \delta V(b(\theta^L)) = \alpha \theta^M U(\omega + b(\theta^H)) + \delta V(b(\theta^H)).
\]
Differentiating this indifference condition with respect to $\theta^H$ yields
\[
\frac{d\theta^M}{d\theta^H} = \frac{db(\theta^H)}{d\theta^H} \frac{U'(\omega + b(\theta^H))}{U(\omega + b(\theta^H)) - U(\omega + b(\theta^L))} \frac{\alpha(\theta^H - \theta^M)}{\alpha(\theta^H - \theta^M)}.
\]
where we have used the private information constraint $\alpha \frac{db(\theta^H)}{d\theta^H} (\theta^H U'(\omega + b(\theta^H)) + \delta V'(b(\theta^H))) = 0$. Substituting back into (A.5), the change in social welfare is
\[
\alpha \frac{db(\theta^H)}{d\theta^H} U'(\omega + b(\theta^H)) \int_{\theta^M}^{\theta^H} (Q(\theta) - Q(\theta^M))d\theta.
\]
Since \( \frac{db_\theta}{db^{\theta_H}} > 0 \), \( U'(\omega + b(\theta^H)) > 0 \), and \( Q'(\theta) > 0 \), this expression is strictly positive. Hence, we obtain that if \( V(b(\theta)) \) is strictly interior and \( Q'(\theta) > 0 \) over a given interval, then \( V(b(\theta)) \) must be a step function over the interval.

**Step 3.** We show that \( V(b(\theta)) \in \{V(b(\theta)), \nabla(b(\theta))\} \) for all \( \theta \in \Theta \).

Suppose by contradiction that \( V(b(\theta)) \in (V(b(\theta)), \nabla(b(\theta))) \) for some \( \theta \in \Theta \). By the previous steps and Lemma 2, type \( \theta \) belongs to a stand-alone segment \((\theta^L, \theta^H]\), such that \( b(\theta) = b \) and \( V(b(\theta)) = V \) for all \( \theta \in (\theta^L, \theta^H] \), \( b \in (b(b_{-1}), \bar{b}(b_{-1})) \) and \( V \in (V(b), \nabla(b)) \) (by assumption), \( b(\theta) \) jumps at \( \theta^L \), and \( b(\theta) \) jumps at \( \theta^H \) unless \( \theta^H = \bar{\theta} \).

We first show that the limited commitment constraint must be slack for all \( \theta \in (\theta^L, \theta^H) \). Express this constraint as the difference between the left-hand and right-hand sides of (8), so that it must be weakly positive and it equals zero if it binds. By the private information constraints, the derivative of the limited commitment constraint with respect to \( \theta \) is \( \alpha U(\omega + b(\theta)) - \alpha U(\omega + b^p(\omega, \theta)) \). Since \( b(\theta) \) is constant over \((\theta^L, \theta^H]\) and \( b^p(\omega, \theta) \) is nondecreasing, it follows that the limited commitment constraint is weakly concave over the interval. Then, if the constraint binds at any interior point \( \theta' \in (\theta^L, \theta^H) \), it must bind at all \( \theta \in (\theta^L, \theta^H) \). However, by the arguments used in Case 2 in Step 2 above, that would require \( b = b^p(\omega, \theta) \) and \( V = V(b) \) for \( \theta \in (\theta^L, \theta^H) \), contradicting the assumption that \( V \) is strictly interior.

We next show that there is an incentive feasible perturbation that strictly increases social welfare. We consider segment-shifting perturbations that marginally change the constant borrowing level \( b \) and continuation value \( V \). There are two cases:

**Case 1:** Suppose \( \int_{\theta^L}^{\theta^H} Q(\theta) d\theta < \int_{\theta^L}^{\theta^H} Q(\theta) d\theta \). Consider a perturbation that marginally changes the borrowing level by \( db > 0 \) and changes \( V \) in order to keep type \( \theta^H \) equally well off. For arbitrarily small \( db > 0 \), this perturbation makes the lowest types in \((\theta^L, \theta^H]\), arbitrarily close to \( \theta^L \), jump either to the allocation of type \( \theta^L \) or to their flexible allocation under maximal punishment \((b^p(\omega, \theta), V(\bar{b}^p(\omega, \theta)))\)), where we let the perturbation introduce the latter. In the limit as \( db \) goes to zero, the change in social welfare is\(^{20}\)

\[
\alpha \int_{\theta^L}^{\theta^H} U'(\omega + b)Q(\theta) d\theta + \alpha \frac{db^L}{db}(U(\omega + b(\theta^L)) - U(\omega + b))Q(\theta^L).
\]

\(^{20}\)The arguments that follow are unchanged if \((b(\theta^L), V(b(\theta^L)))\) is replaced with \((b^p(\omega, \theta^L), V(\bar{b}^p(\omega, \theta^L)))\) for the cases where the limited commitment constraint binds.
The perturbation satisfies
\[ db \alpha \theta^H U'(\omega + b) + \delta dV = 0, \quad \text{(A.7)} \]
and the following indifference condition for type $\theta^L$:
\[ \alpha \theta^L U(\omega + b) + \delta V(b) = \alpha \theta^L U(\omega + b(\theta^L)) + \delta V(b(\theta^L)). \]

To verify that the perturbation is incentive feasible for $db$ arbitrarily close to zero, note that the limited commitment constraint is slack for all $\theta \in (\theta^L, \theta^H)$, $V$ is strictly interior, and the government welfare of types $\theta^L$ and $\theta^H$ remains unchanged with the perturbation.

To verify that the perturbation strictly increases social welfare, note that differentiating the indifference condition of type $\theta^L$ and substituting with (A.7) yields
\[ \frac{d\theta^L}{db} = -U'(\omega + b) \frac{\left( \theta^H - \theta^L \right)}{U(\omega + b(\theta^L)) - U(\omega + b)}. \]
Substituting back into (A.6), the change in social welfare is
\[ \alpha U'(\omega + b) \int_{\theta^L}^{\theta^H} (Q(\theta) - Q(\theta^L)) d\theta. \]

Since $U'(\omega + b) > 0$ and by assumption $\int_{\theta^L}^{\theta^H} Q(\theta^L) d\theta < \int_{\theta^L}^{\theta^H} Q(\theta) d\theta$, the above expression is strictly positive. The claim follows.

**Case 2:** Suppose $\int_{\theta^L}^{\theta^H} Q(\theta^L) d\theta \geq \int_{\theta^L}^{\theta^H} Q(\theta) d\theta$. By the generic property in Proposition 1, there exists $\theta^h \in (\theta^L, \theta^H]$ such that $\int_{\theta^L}^{\theta^h} Q(\theta^L) d\theta < \int_{\theta^L}^{\theta^h} Q(\theta) d\theta$. Then consider a perturbation where, for $\theta \in (\theta^L, \theta^h]$, we change the borrowing level by $-db < 0$ arbitrarily close to zero and change $V$ in order to keep type $\theta^h$ equally well off. This perturbation makes types arbitrarily close to $\theta^L$ jump up to the allocation of the stand-alone segment. Arguments analogous to those in Case 1 above imply that the perturbation is incentive feasible. Moreover, following analogous steps as in that case yields that the implied change in social welfare is
\[ -\alpha U'(\omega + b) \int_{\theta^L}^{\theta^h} (Q(\theta) - Q(\theta^L)) d\theta. \]
Since $U'(\omega + b) > 0$ and by assumption $\int_{\overline{\theta}}^{\theta} Q(\theta^L)d\theta > \int_{\theta}^{\overline{\theta}} Q(\theta)d\theta$, the above expression is strictly positive. The claim follows.

**Lemma 4.** If $(b(\theta), V(b(\theta)))$ is a solution to $(P_{\text{min}})$ with $b(\theta) \in (b(b_{-1}), \overline{b}(b_{-1}))$ for all $\theta \in \Theta$, then $V(b(\theta)) \in \{\underline{V}(b(\theta)), \overline{V}(b(\theta))\}$ for all $\theta \in \Theta$.

**Proof.** The proof of this lemma is analogous to the proof of Lemma 3. We therefore describe this proof only briefly here, focusing on the steps that are different.

Take any solution $(b(\theta), V(b(\theta)))$ to $(P_{\text{min}})$ with $b(\theta) \in (b(b_{-1}), \overline{b}(b_{-1}))$ for all $\theta \in \Theta$. By analogous arguments to those in the first part of Step 1 in the proof of Lemma 3, we can establish that $V(b(\theta))$ must be right-continuous at each $\theta \in [\theta, \overline{\theta}]$. Moreover, by arguments analogous to those in the second part of Step 1, we can establish that $V(b(\theta)) = \overline{V}(b(\theta))$. Specifically, if $V(b(\theta)) \in (\underline{V}(b(\theta)), \overline{V}(b(\theta)))$, then a perturbation that marginally increases $b(\theta) \in (b, \overline{b})$ and changes $V(b(\theta))$ so as to keep type $\overline{\theta}$'s welfare unchanged is incentive feasible and strictly reduces social welfare. Such a perturbation is also incentive feasible (and welfare reducing) if $V(b(\theta)) = V(b(\theta))$, as in this case $b(\theta) = b^*(\omega, \theta)$ by the limited commitment constraint (8) and thus the perturbation requires setting $V(b(\theta)) > V(b(\theta))$. It follows that $V(b(\theta)) = V(b(\theta))$.

The claims in Step 2 and Step 3 in the proof of Lemma 3 also apply when solving program $(P_{\text{min}})$. The reason is that perturbations that apply whenever $Q'(\theta) > 0$ in the maximization of social welfare now apply whenever $Q'(\theta) < 0$ in the minimization of social welfare, and vice versa. Hence, the arguments in these steps, together with those in Step 1 just described, imply that $V(b(\theta)) \in \{\underline{V}(b(\theta)), \overline{V}(b(\theta))\}$ for all $\theta \in [\theta, \overline{\theta}]$ in any solution to $(P_{\text{min}})$ with $b(\theta) \in (b(b_{-1}), \overline{b}(b_{-1}))$ for all $\theta \in \Theta$. 

### A.3 Proof of Proposition 2

We first prove Lemma 5 and Lemma 6 and then proceed with the proof of the proposition.

**Lemma 5.** If $(b(\theta), V(b(\theta)))$ is a maximally enforced deficit limit, it satisfies the private information constraint (7) and the limited commitment constraint (8).

**Proof.** We proceed in three steps.

**Step 1.** Suppose $\theta^* \geq \theta$. We show that (7) and (8) are satisfied for $\theta \in [\theta, \theta^*]$. 

The claim follows immediately from the fact that all types $\theta \in [\theta, \theta^*]$ are assigned their flexible debt levels with the highest continuation value. Thus, given $\theta \in [\theta, \theta^*]$, type $\theta$’s welfare cannot be increased, so (7) and (8) are trivially satisfied.

**Step 2.** We show that (7) and (8) are satisfied for $\theta \in (\theta^*, \theta^{**}]$.

Take first the limited commitment constraint (8). We can rewrite it for $\theta \in (\theta^*, \theta^{**}]$ as

$$\alpha \theta U(\omega + b^*(\omega, \theta^*)) + \delta V(b^*(\omega, \theta^*)) - \alpha \theta U(\omega + b^p(\omega, \theta)) - \delta V(b^p(\omega, \theta)) \geq 0. \quad \text{(A.8)}$$

Differentiating the left-hand side with respect to $\theta$, given $\theta^*$ and the definition of $b^p(\omega, \theta)$, yields

$$\alpha U(\omega + b^*(\omega, \theta^*)) - \alpha U(\omega + b^p(\omega, \theta)),$$

which is weakly decreasing in $\theta$, since $b^p(\omega, \theta)$ is nondecreasing. This means that the left-hand side of (A.8) is weakly concave. Since (A.8) holds as a strict inequality for $\theta = \theta^*$ and as an equality for $\theta = \theta^{**}$ (by (13)), this weak concavity implies that (A.8) holds as a strict inequality for all $\theta \in (\theta^*, \theta^{**})$. Thus, constraint (8) is satisfied for all $\theta \in (\theta^*, \theta^{**}]$.

Take next the private information constraint (7). This constraint is trivially satisfied for all $\theta \in (\theta^*, \theta^{**}]$ given $\theta' \in [\theta^*, \theta^{**}]$, since all types $\theta \in [\theta^*, \theta^{**}]$ are prescribed the same level of debt and continuation value. We next show that the constraint is also satisfied given $\theta' > \theta^{**}$ and $\theta' < \theta^*$:

**Step 2a:** We show that (7) is satisfied for all $\theta \in (\theta^*, \theta^{**}]$ given $\theta' > \theta^{**}$. Note that

$$(b(\theta'), V(b(\theta')))) = (b^p(\omega, \theta'), V(b^p(\omega, \theta'))))$$

for all $\theta' > \theta^{**}$, and by the definition of $b^p(\omega, \theta)$,

$$\alpha \theta U(\omega + b^p(\omega, \theta)) + \delta V(b^p(\omega, \theta)) \geq \alpha \theta U(\omega + b^p(\omega, \theta')) + \delta V(b^p(\omega, \theta'))$$

for all $\theta' \in \Theta$. Thus, the fact that the limited commitment constraint (8) is satisfied for all $\theta \in (\theta^*, \theta^{**}]$ implies that (7) is satisfied for all such types given $\theta' > \theta^{**}$.

**Step 2b:** We show that (7) is satisfied for all $\theta \in (\theta^*, \theta^{**}]$ given $\theta' < \theta^*$. Suppose by contradiction that this is not the case, that is,

$$\alpha \theta(U(\omega + b^*(\omega, \theta^*)) - U(\omega + b^*(\omega, \theta'))) < \delta (V(b^*(\omega, \theta')) - V(b^*(\omega, \theta^*))) \quad \text{(A.9)}$$
for some \( \theta \in (\theta^*, \theta^{**}] \) and \( \theta' < \theta^* \). By Step 1, (7) holds for type \( \theta^* \) given \( \theta' < \theta^* \):

\[
\alpha \theta^*(U(\omega + b^*(\omega, \theta^*)) - U(\omega + b^*(\omega, \theta'))) \geq \delta (V(b^*(\omega, \theta^*)) - V(b^*(\omega, \theta^*))). \tag{A.10}
\]

Combining (A.9) and (A.10) yields

\[
\alpha(\theta^* - \theta)(U(\omega + b^*(\omega, \theta^*)) - U(\omega + b^*(\omega, \theta'))) > 0,
\]

which is a contradiction since \( \theta > \theta^* \) and \( b^*(\omega, \theta') \leq b^*(\omega, \theta^*) \). The claim follows.

**Step 3.** Suppose \( \theta^{**} < \hat{\theta} \). We show that (7) and (8) are satisfied for \( \theta \in (\theta^{**}, \hat{\theta}] \).

Constraint (8) is satisfied as an equality for all \( \theta \in (\theta^{**}, \hat{\theta}] \). It is immediate that constraint (7) is satisfied for all \( \theta \in (\theta^{**}, \hat{\theta}] \) given \( \theta' \in (\theta^{**}, \hat{\theta}] \), since all such types are prescribed their flexible debt level with the lowest continuation value. Consider next constraint (7) for \( \theta \in (\theta^{**}, \hat{\theta}] \) given \( \theta' \in [\theta^*, \theta^{**}] \). Note that \((b(\theta'), V(b(\theta'))) = (b^*(\omega, \theta^*), V(b^*(\omega, \theta^*)))\) for all \( \theta' \in [\theta^*, \theta^{**}] \). Thus, satisfaction of this constraint is ensured if (A.8) is violated for \( \theta \in (\theta^{**}, \hat{\theta}] \). The latter is true since, as shown above, the left-hand side of (A.8) is weakly concave and (A.8) holds as an equality for \( \theta = \theta^{**} \) and a strict inequality for \( \theta \in (\theta^*, \theta^{**}) \).

Finally, consider constraint (7) for \( \theta \in (\theta^{**}, \hat{\theta}] \) given \( \theta' < \theta^* \). Since (7) is satisfied given \( \theta' \in [\theta^*, \theta^{**}] \), satisfaction of this constraint given \( \theta' < \theta^* \) is ensured if

\[
\alpha \theta(U(\omega + b^*(\omega, \theta^*)) - U(\omega + b^*(\omega, \theta'))) \geq \delta (V(b^*(\omega, \theta^*)) - V(b^*(\omega, \theta^*)))
\]

for \( \theta \in (\theta^{**}, \hat{\theta}] \). The latter follows from the same logic as in Step 2b above. \( \square \)

**Lemma 6.** If \((b(\theta), V(b(\theta)))\) is a solution to \((P_{\text{max}})\) with \(b(\theta) \in (\underline{b}(b_{-1}), \overline{b}(b_{-1}))\) for all \( \theta \in \Theta \), then either \( V(b(\theta)) = V(b(\theta)) \) for all \( \theta \in \Theta \), or there exists \( \theta^{**} \in (\underline{\theta}, \overline{\theta}) \) such that \( V(b(\theta)) = V(b(\theta)) \) for all \( \theta \in [\underline{\theta}, \theta^{**}] \) and \( V(b(\theta)) = V(b(\theta)) \) for all \( \theta \in (\theta^{**}, \overline{\theta}] \).

**Proof.** Take any solution \((b(\theta), V(b(\theta)))\) to \((P_{\text{max}})\) with \(b(\theta) \in (\underline{b}(b_{-1}), \overline{b}(b_{-1}))\) for all \( \theta \in \Theta \). We proceed in three steps.

**Step 1.** We show that if \( V(b(\theta^{**})) = \underline{V}(b(\theta^{**})) \), then \( \theta^{**} \geq \hat{\theta} \).
By Lemma 3 and Step 1 in the proof of that lemma, if \( V(b(\theta^{**})) = V(b(\theta^{**})) \) for some \( \theta^{**} \in \Theta \), then \( V(b(\theta)) = V(b(\theta)) \) over an interval \((\theta^L, \theta^H]\) that contains \( \theta^{**} \). Take the largest such interval. We establish that \( \theta^L \geq \tilde{\theta} \).

Suppose by contradiction that \( \theta^L < \tilde{\theta} \). Note that constraint (8) requires \( b(\theta) = b^p(\omega, \theta) \) for all \( \theta \in (\theta^L, \theta^H] \), and the strict concavity of \( V(\cdot) \) implies that \( b^p(\omega, \theta) \) is strictly increasing over a subset of \((\theta^L, \theta^H]\) below \( \tilde{\theta} \). Without loss, take such a subset with \( b^p(\omega, \theta) \) being continuously differentiable. Then we can perform a flattening perturbation that rotates the borrowing schedule clockwise over this subset, analogous to the perturbation used in Step 2 (Case 1) in the proof of Lemma 3. By the arguments in that step, this perturbation is incentive feasible. In particular, note that since the perturbation weakly increases the government welfare of all types \( \theta \) in the subset while simultaneously changing their borrowing allocation, it follows from the definition of \( b^p(\omega, \theta) \) that the perturbation must necessarily increase \( V(b(\theta)) \) above \( V(b(\theta)) \). Furthermore, by \( Q'(\theta) < 0 \) for all types \( \theta \) in the subset (by the subset being below \( \tilde{\theta} \) and Assumption 2), the perturbation strictly increases social welfare, yielding a contradiction.

**Step 2.** We show that if \( V(b(\theta^{**})) = V(b(\theta^{**})) \), then \( V(b(\theta)) = V(b(\theta)) \) for all \( \theta \geq \theta^{**} \).

Suppose by contradiction that \( V(b(\theta^{**})) = V(b(\theta^{**})) \) for \( \theta^{**} \in \Theta \) and \( V(b(\theta)) > V(b(\theta)) \) for some \( \theta > \theta^{**} \). By Step 1, \( \theta^{**} \geq \tilde{\theta} \). Moreover, by Lemma 3 and Step 1 in the proof of that lemma, there exist \( \theta^H > \theta^L \geq \theta^{**} \) such that \( V(b(\theta)) = V(b(\theta)) \) for all \( \theta \in (\theta^L, \theta^H] \).

We begin by establishing that \( b(\theta) = b \) for all \( \theta \in (\theta^L, \theta^H] \) and some \( b \in (b(b_{-1}), b(b_{-1})) \). Suppose by contradiction that \( b(\theta) \) is strictly increasing at some point \( \theta' \in (\theta^L, \theta^H] \). Note that the private information constraint (7) implies \( b(\theta) = b^r(\omega, \theta) \), and thus a slack limited commitment constraint (8), in the neighborhood of such a type \( \theta' \). Then we can perform an incentive feasible steepening perturbation that drills a hole in the \( b(\theta) \) schedule in this neighborhood, as that described in Step 2 (Case 2) in the proof of Lemma 3. By the arguments in that step, this perturbation strictly increases social welfare, yielding a contradiction.

We next show that a segment \((\theta^L, \theta^H] \) with \( b(\theta) = b \) and \( V(b(\theta)) = V(b(\theta)) \) for all \( \theta \in (\theta^L, \theta^H] \) and \( \theta^L \geq \theta^{**} \) cannot exist. Suppose by contradiction that it does. Take \( \theta^L \) to be the lowest point weakly above \( \theta^{**} \) at which \( V(b(\theta)) \) jumps, and take \( \theta^H \) to be
the lowest point above \( \theta^L \) at which \( V(b(\theta)) \) jumps again, or \( \theta^L = \bar{\theta} \) if \( V(b(\theta)) \) does not jump above \( \theta^L \). Then \( [\theta^L, \theta^H] \) is a stand-alone segment with constant borrowing \( b \) and continuation value \( V = \overline{V} (b) \). By arguments analogous to those in Step 3 of the proof of Lemma 3, the limited commitment constraint must be slack for all \( \theta \in (\theta^L, \theta^H) \).

We then show that there is an incentive feasible segment-shifting perturbation that is socially beneficial. There are three cases to consider:

**Case 1:** Suppose \( \alpha \theta^H U(\omega + b) + \delta \overline{V}(b) \leq \alpha \theta^H U(\omega + b') + \delta \overline{V}(b') \) for \( b' = b + \varepsilon, \varepsilon > 0 \) arbitrarily small. Then we perform a segment-shifting perturbation as that in Step 3 (Case 1) in the proof of Lemma 3, where we marginally increase \( b \) and reduce \( V(b) \) marginally below \( \overline{V}(b) \) so as to keep type \( \theta^H \)'s welfare unchanged. This perturbation is incentive feasible. Moreover, since \( \theta^L \geq \theta^{**} \) and Assumption 2 imply \( \int_{\theta^L}^{\theta^H} Q(\theta^L) d\theta < \int_{\theta^L}^{\theta^H} Q(\theta) d\theta \), this perturbation strictly increases social welfare, yielding a contradiction.

**Case 2:** Suppose \( \alpha \theta^H U(\omega + b) + \delta \overline{V}(b) > \alpha \theta^H U(\omega + b') + \delta \overline{V}(b') \) for \( b' = b + \varepsilon, \varepsilon > 0 \) arbitrarily small, and \( \theta^H < \bar{\theta} \). Then we perform a segment-shifting perturbation that marginally changes the borrowing level by \( -db < 0 \) and reduces \( V \) marginally below \( \overline{V}(b) \) so as to keep type \( \theta^L \)'s welfare unchanged. This perturbation is incentive feasible. Denote by \( (b(\theta^h), V(b(\theta^h))) \) the allocation above \( \theta^H \) over which type \( \theta^H \) is initially indifferent. Note that analogous to the perturbation in Step 3 in the proof of Lemma 3, this perturbation makes the highest types in \( (\theta^L, \theta^H) \), arbitrarily close to \( \theta^H \), jump either to \( (b(\theta^h), V(b(\theta^h))) \) or to their flexible allocation under the maximal punishment \( (b^p(\omega, \theta), \overline{V}(b^p(\omega, \theta))) \), where we let the perturbation introduce the latter. In the limit as \( db \) goes to zero, the change in social welfare is\(^{21}\)

\[
- \alpha \int_{\theta^L}^{\theta^H} U'(\omega + b) Q(\theta) d\theta + \alpha \frac{db^H}{db} (U(\omega + b(\theta^h)) - U(\omega + b)) Q(\theta^H).
\]

The perturbation satisfies

\[
db \alpha \theta^L U'(\omega + b) + \delta V = 0,
\]

\(^{21}\)The arguments that follow are unchanged if \( (b(\theta^h), V(b(\theta^h))) \) is replaced with \( (b^p(\omega, \theta^H), \overline{V}(b^p(\omega, \theta^H))) \) for the cases where the limited commitment constraint binds.
and the following indifference condition for type $\theta^H$:

$$\alpha \theta^H U(\omega + b) + \delta V(b) = \alpha \theta^H U(\omega + b(\theta^h)) + \delta V(b(\theta^h)).$$

Differentiating this indifference condition and substituting with (A.12) yields

$$\frac{d \theta^H}{db} = U'(\omega + b) \frac{(\theta^H - \theta^L)}{U(\omega + b(\theta^h)) - U(\omega + b)}.$$

Substituting back into (A.11), the change in social welfare is

$$-\alpha U'(\omega + b) \int_{\theta^L}^{\theta^H} (Q(\theta) - Q(\theta^H))d\theta.$$

Since $U'(\omega + b) > 0$ and $Q'(\theta) > 0$ over $[\theta^L, \theta^H]$ given $\theta^L \geq \theta^*\text{**, this expression is strictly positive. Thus, the perturbation strictly increases social welfare, yielding a contradiction.}

**Case 3:** Suppose $\alpha \theta^H U(\omega + b) + \delta V(b) > \alpha \theta^H U(\omega + b') + \delta V(b')$ for $b' = b + \varepsilon$, $\varepsilon > 0$ arbitrarily small, and $\theta^H = \overline{\theta}$. Then we perform a segment-shifting perturbation as that in Case 2 above, where we marginally reduce $b$ and decrease $V$ marginally below $V(b)$ so as to keep type $\theta^L$’s welfare unchanged. This perturbation is incentive feasible. Note that analogous to Case 2, this perturbation makes the highest types in $(\theta^L, \theta^H]$, arbitrarily close to $\theta^H$, either jump to their flexible allocation under maximal punishment $(b(\omega, \theta), V(b(\omega, \theta)))$ or remain with the perturbed allocation. In the former case, the same arguments as in Case 2 apply, yielding that the perturbation strictly increases social welfare by $-\alpha U'(\omega + b) \int_{\theta^L}^{\theta^H} (Q(\theta) - Q(\theta^H))d\theta > 0$. In the latter case, those arguments imply that the change in social welfare is equal to $-\alpha U'(\omega + b) \int_{\theta^L}^{\theta^H} Q(\theta)d\theta$, which is strictly positive since $Q(\overline{\theta}) \leq 0$ and $Q'(\theta) > 0$ over $[\theta^L, \theta^H]$. Hence, the perturbation strictly increases social welfare, yielding a contradiction.

**Step 3.** We show that $V(b(\theta))$ is right-continuous at $\overline{\theta}$.

Suppose by contradiction that this is not the case. Then by the previous steps, Lemma 3, and Step 1 in the proof of that lemma, $V(b(\theta)) = V(b(\overline{\theta}))$ for all $\theta \in (\overline{\theta}, \overline{\theta}]$ and $V(b(\theta))$ jumps down at $\overline{\theta}$ from $V(b(\theta))$. Note that constraint (8) implies $b(\theta) = \overline{\theta}$.
Take $\Delta \in (0, \min_{\theta \in \Theta} \{V(b(\theta)) - V(b(\theta))\})$. Consider a global perturbation that assigns $V(b(\theta)) = V(b(\theta)) + \Delta$ to all $\theta \in (\theta, \tilde{\theta}]$ and assigns type $\theta$ the limit allocation to its right. This perturbation keeps borrowing unchanged for types $\theta \in (\theta, \tilde{\theta}]$ and is incentive feasible. Moreover, using the representation in (11), the change in social welfare from this perturbation is equal to $\delta \Delta$. Thus, the perturbation strictly increases social welfare, yielding a contradiction. 

**Proof of Proposition 2.** We now proceed to prove the proposition. Take any solution $(b(\theta), V(b(\theta)))$ to $(P_{\text{max}})$ with $b(\theta) \in (b(b_{-1}), b(b_{-1}))$ for all $\theta \in \Theta$. By Lemma 6 and the limited commitment constraint (8), there exists $\theta^{**} > \tilde{\theta}$ such that $(b(\theta), V(b(\theta))) = (b^p(\omega, \theta), V(b^p(\omega, \theta)))$ for all $\theta > \theta^{**}$ and $V(b(\theta)) = \overline{V}(b(\theta))$ for all $\theta \leq \theta^{**}$ (where it is possible that $\theta^{**} > \tilde{\theta}$). Moreover, since the limited commitment constraint holds with equality at $\theta^{**}$, this type’s allocation satisfies

$$\alpha \theta^{**} U(\omega + b(\theta^{**})) + \delta \overline{V}(b(\theta^{**})) = \alpha \theta^{**} U(\omega + b^p(\omega, \theta^{**})) + \delta \overline{V}(b^p(\omega, \theta^{**})). \quad (A.13)$$

These results characterize the allocation for types $\theta \geq \theta^{**}$. To characterize the allocation for types $\theta < \theta^{**}$, we proceed in three steps.

**Step 1.** We show that $b(\theta)$ is continuous over $[\theta, \theta^{**}]$.

By Step 1 in the proof of Lemma 6, $\theta^{**} \geq \tilde{\theta}$. There are two cases to consider:

**Case 1:** Suppose by contradiction that $b(\theta)$ has a point of discontinuity below $\tilde{\theta}$: there is a type $\theta^M < \tilde{\theta}$ which is indifferent between choosing $\lim_{\theta \to \theta^M} b(\theta)$ and $\lim_{\theta \to \theta^M} b(\theta) > \lim_{\theta \to \theta^M} b(\theta)$. Note that given $V(b(\theta)) = \overline{V}(b(\theta))$ for all $\theta \in [\theta, \theta^{**}]$ and $\theta^{**} \geq \tilde{\theta}$, there must be a hole with types $\theta \in [\theta^L, \theta^M]$ bunched at $b^r(\omega, \theta^L)$ and types $\theta \in (\theta^M, \theta^H]$ bunched at $b^r(\omega, \theta^H)$, for some $\theta^L < \theta^M < \theta^H$. Now consider perturbing the allocation by marginally increasing $\theta^L$, in an effort to slightly close the hole. This perturbation leaves the government welfare of types strictly above $\theta^M$ unchanged and is incentive
feasible. The change in social welfare is

\[ \alpha \int_{\theta^L}^{\theta^M} \frac{db^r(\omega, \theta^L)}{d\theta^L} U'(\omega + b^r(\omega, \theta^L)) Q(\theta) d\theta + \alpha \frac{d\theta^M}{d\theta^L} \left( U(\omega + b^r(\omega, \theta^L)) - U(\omega + b^r(\omega, \theta^H)) \right) Q(\theta^M). \]

(A.14)

By indifference of type \( \theta^M \),

\[ \alpha \theta^M U(\omega + b^r(\omega, \theta^L)) + \delta V(b^r(\omega, \theta^L)) = \alpha \theta^M U(\omega + b^r(\omega, \theta^H)) + \delta V(b^r(\omega, \theta^H)). \]

Differentiating this indifference condition with respect to \( \theta^L \) yields

\[ \frac{d\theta^M}{d\theta^L} = \frac{\frac{d\theta^M}{d\theta^L} U'(\omega + b^r(\omega, \theta^L))}{U(\omega + b^r(\omega, \theta^H)) - U(\omega + b^r(\omega, \theta^L))}, \]

where we have used the fact that \( \alpha \theta^L U'(\omega + b^r(\omega, \theta^L)) = -\delta V'(b^r(\omega, \theta^L)) \). Substituting back into (A.14), the change in social welfare is

\[ \alpha \int_{\theta^L}^{\theta^M} \frac{db^r(\omega, \theta^L)}{d\theta^L} U'(\omega + b^r(\omega, \theta^L)) \left( Q(\theta) - Q(\theta^M) \right) d\theta. \]

Since \( \frac{db^r(\omega, \theta^L)}{d\theta^L} > 0 \), \( U'(\omega + b^r(\omega, \theta^L)) > 0 \), and \( Q'(\theta) < 0 \) over \( \theta \in [\theta^L, \theta^M] \) given \( \theta^M < \hat{\theta} \), this expression is strictly positive. Thus, the perturbation strictly increases social welfare, showing that \( b(\theta) \) cannot jump at a point below \( \hat{\theta} \).

**Case 2:** Suppose by contradiction that \( b(\theta) \) is discontinuous at a point \( \theta \in [\hat{\theta}, \theta^{**}] \). Note that since \( V(b(\theta)) = \overline{V}(b(\theta)) \) for all \( \theta \in [\hat{\theta}, \theta^{**}] \), we can apply the same logic as in Step 2 in the proof of Lemma 6 to show that \( \frac{db(\theta)}{d\theta} = 0 \) over any continuous interval in \( [\hat{\theta}, \theta^{**}] \). Hence, if \( b(\theta) \) jumps at a point \( \theta \in [\hat{\theta}, \theta^{**}] \), then there exists a stand-alone segment \( (\theta^L, \theta^H) \) with constant borrowing \( b \in (b(b_{-1}), \overline{b}(b_{-1})) \) and continuation value \( V = \overline{V}(b) \), satisfying \( \theta^L \geq \hat{\theta} \). However, using again the arguments in Step 2 in the proof of Lemma 6, we can then perform an incentive feasible segment-shifting perturbation that strictly increases social welfare. Thus, \( b(\theta) \) cannot jump at a point \( \theta \in [\hat{\theta}, \theta^{**}] \).

**Step 2.** We show that \( b(\theta) \leq b^r(\omega, \theta) \) for all \( \theta \in [\hat{\theta}, \theta^{**}] \).

\(^{22}\)Note that this welfare representation is valid even if \( \theta^L < \hat{\theta} \), as we can apply the envelope condition in (10) from any positive \( \theta' < \hat{\theta} \). For \( \theta < \hat{\theta} \), we have \( Q(\hat{\theta}) = 1 \).
By Step 1 above, the allocation over \([\theta, \theta^*]\) must be bounded discretion, with either a minimum borrowing level or a maximum borrowing level or both. We next show that a binding minimum borrowing requirement is strictly suboptimal. Suppose by contradiction that this is not the case, namely there exist \(\theta^* > \theta\) and an optimal allocation prescribing \((b(\theta), V(b(\theta))) = (b^r(\omega, \theta^*), \nabla(b^r(\omega, \theta^*)))\) for all \(\theta \in [\theta, \theta^*]\), where \(b^r(\omega, \theta) < b^r(\omega, \theta^*)\) for all \(\theta \in [\theta, \theta^*]\). Consider a perturbation where we remove this minimum borrowing requirement, that is, we set \((b(\theta), V(b(\theta))) = (b_r(\omega, \theta), \nabla(b_r(\omega, \theta)))\) for all \(\theta \in [\theta, \theta^*]\). Clearly, this perturbation is incentive feasible, and it keeps the allocation of types \(\theta \in [\theta^*, \theta]\), and thus the social welfare from these types, unchanged. The change in social welfare from each type \(\theta \in [\theta, \theta^*]\) is

\[
\theta U(\omega + b^r(\omega, \theta)) + \delta \nabla(b^r(\omega, \theta)) - \theta U(\omega + b^r(\omega, \theta^*)) - \delta \nabla(b^r(\omega, \theta^*)).
\]

Note that by the definition of \(b^r(\omega, \theta)\),

\[
\delta \nabla(b^r(\omega, \theta)) - \delta \nabla(b^r(\omega, \theta^*)) \geq \alpha (\theta U(\omega + b^r(\omega, \theta^*)) - \theta U(\omega + b^r(\omega, \theta))).
\]

Substituting back into the previous expression, we obtain that the change in social welfare from each \(\theta \in [\theta, \theta^*]\) is greater than

\[
(\alpha - 1) (\theta U(\omega + b^r(\omega, \theta^*)) - \theta U(\omega + b^r(\omega, \theta))),
\]

which is strictly positive. Thus, the perturbation strictly increases social welfare, implying that a binding minimum borrowing requirement is strictly suboptimal.

**Step 3.** We show that \(b(\theta) < b^r(\omega, \theta)\) for some \(\theta \in \Theta\).

By Step 1 and Step 2, the allocation for types \(\theta \in [\theta, \theta^*]\) is as described in Definition 1 for some \(\theta^* \geq 0\). That is, equation (A.13) necessarily holds for \(b(\theta^*) = b^r(\omega, \theta^*)\). All that remains to be shown is that \(\theta^* < \theta\). Suppose by contradiction that this is not true, which implies \((b(\theta), V(b(\theta))) = (b^r(\omega, \theta), \nabla(b^r(\omega, \theta)))\) for all \(\theta \in \Theta\). Consider an incentive feasible perturbation that assigns \((b(\theta), V(b(\theta))) = (b^r(\omega, \theta - \varepsilon), \nabla(b^r(\omega, \theta - \varepsilon)))\) to all \(\theta \in [\theta - \varepsilon, \theta]\), where \(\varepsilon > 0\) is chosen to be small enough as to continue to satisfy the limited commitment constraint (8) for all types.
\[ \theta \in \Theta. \text{ Using the representation in (11), the change in social welfare is} \]
\[ \alpha \int_{\theta - \varepsilon}^{\theta} (U(\omega + b'(\omega, \theta - \varepsilon)) - U(\omega + b'(\omega, \theta))) Q(\theta) d\theta. \]

For \( \varepsilon > 0 \) arbitrarily small, \( b'(\omega, \theta - \varepsilon) < b'(\omega, \theta) \) and \( Q(\theta) < 0 \) for all \( \theta \in (\theta - \varepsilon, \theta) \). Thus, the perturbation strictly increases social welfare, proving the claim.

### A.4 Proof of Proposition 3

The proof of this proposition is analogous to the proof of Proposition 2. We therefore describe this proof only briefly here, focusing on the steps that are different.

Analogous arguments to those in Lemma 5 imply that if \((b(\theta), V(b(\theta)))\) is a maximally enforced surplus limit, then it satisfies the private information and limited commitment constraints in program \((P_{\text{min}})\). Consider next the proof of Lemma 6.

Step 1 and Step 2 in that proof can be applied isomorphically to \((P_{\text{min}})\) in the sense that the arguments applying to types \( \theta < \widehat{\theta} \) in the maximization of social welfare now apply to types \( \theta > \widehat{\theta} \) in the minimization of social welfare, and vice versa. Combined with the claims above, these steps thus imply the following: in any solution \((b(\theta), V(b(\theta)))\) to \((P_{\text{min}})\) with \( b(\theta) \in (b(b_{-1}), \widehat{b}(b_{-1})) \) for all \( \theta \in \Theta \), there exists \( \theta^{**}_n \leq \widehat{\theta} \) such that \( V(b(\theta)) = V(\widehat{b}(\theta)) \) for all \( \theta \in [\theta, \theta^{**}_n) \) and \( V(\widehat{b}(\theta)) = V(\widehat{b}(\theta)) \) for all \( \theta \in [\theta^{**}_n, \widehat{\theta}] \).

The analog of Step 3 in the proof of Lemma 6 consists of showing that \( \theta^{**}_n < \widehat{\theta} \). To see why this must be true, suppose by contradiction that \( \theta^{**}_n = \widehat{\theta} \), namely that \( V(\widehat{b}(\theta)) = V(\widehat{b}(\theta)) \) for all \( \theta \in [\theta, \widehat{\theta}] \) and \( V(\widehat{b}(\theta)) \) jumps at \( \widehat{\theta} \) to \( V(\widehat{b}(\widehat{\theta})) \). Note that the limited commitment constraint (8) implies \( b(\theta) = b^*(\omega, \theta) \) for all \( \theta \in [\theta, \widehat{\theta}] \), and using the representation in (11), social welfare is equal to

\[ \alpha \widehat{\theta} U(\omega + b^*(\omega, \widehat{\theta})) + \delta \widehat{V}(b^*(\omega, \widehat{\theta})) + \alpha \int_{\theta}^{\widehat{\theta}} U(\omega + b^*(\omega, \theta)) Q(\theta) d\theta. \]  
(A.15)

Consider a global perturbation in which all types \( \theta \in \Theta \) are assigned the allocation corresponding to a maximally enforced surplus limit \( \{\theta^*_n, \theta^{**}_n\} \), with \( \theta^{**}_n \in (\theta, \widehat{\theta}) \), \( Q(\theta^{**}_n) < 0 \), and \( \theta^*_n \geq \widehat{\theta} \) (and with equation (15) being satisfied). Note that this is feasible since \( Q(\widehat{\theta}) \) is continuous. Using the representation in (A.15) and taking into account that the perturbation keeps the allocation of types \( \theta \in [\theta, \theta^{**}_n) \),
unchanged, we find that the change in social welfare from the perturbation is equal to
\[
\alpha \int_{\theta_n^*}^{\bar{\theta}} (U(\omega + b^*(\omega, \theta_n^*)) - U(\omega + b^*(\omega, \theta))) Q(\theta) d\theta.
\] (A.16)

Note that \(b^*(\omega, \theta_n^*) > b^p(\omega, \theta)\) and \(Q(\theta) < 0\) for all \(\theta \in [\theta_n^*, \bar{\theta}]\) (by construction, Assumption 2, and the surplus limit satisfying the private information and limited commitment constraints). Hence, the perturbation strictly reduces social welfare, implying that \(\theta_n^* < \bar{\theta}\) must hold in any solution to \((P_{min})\).

Given the claims above, the next step to prove Proposition 3 is to show that \(b(\theta)\) is continuous for \(\theta \geq \theta_n^*\). Here analogous arguments to those in the proof of Proposition 2 apply. The optimality of a surplus limit that is binding (i.e., with \(\theta_n^* > \bar{\theta}\)) also follows from analogous arguments as in that proof. Finally, note that the optimal surplus limit must satisfy \(\theta_n^* \geq \bar{\theta}\): otherwise, if \(\theta_n^* < \bar{\theta}\), then a perturbation that tightens the limit by raising \(\theta_n^*\) to \(\bar{\theta}\) (and raising \(\theta^*_n\) so as to satisfy the indifference condition in (15)) is incentive feasible and strictly reduces social welfare.

## B Proofs for Section 5

### B.1 Preliminaries

We begin by establishing the properties discussed in Subsection 5.1. Take \(U(\cdot) = \log(\cdot)\). We consider a representation of equilibrium using savings rates, as defined in the text. Note that for any period \(t \in \{0, 1, \ldots\}\) and history of debt \(h^{t-1} = \{b_{-1}, b_0, \ldots, b_{t-1}\}\), there is a corresponding history of initial debt and subsequent savings rates, \(\tilde{h}^{t-1} = \{b_{-1}, s_0, \ldots, s_{t-1}\}\). Moreover, a strategy for the government in period \(t\) can be equivalently defined as specifying either a debt level \(b_t(h^{t-1}, \theta_t)\) for each history \(h^{t-1}\) and government type \(\theta_t\), or a savings rate \(s_t(\tilde{h}^{t-1}, \theta_t)\) for each history \(\tilde{h}^{t-1}\) and government type \(\theta_t\). It is thus without loss to redefine strategies and payoffs to condition on \(\tilde{h}^{t-1}\), with \(V_t(\tilde{h}^{t-1})\) denoting the continuation value at \(\tilde{h}^{t-1}\).

Observe that (16) implies that the continuation value at any given history is separable in the inherited level of debt. As a consequence, the private information and limited commitment constraints (3) and (6) are independent of initial debt, implying that whether or not a profile of saving rate strategies constitutes an equilibrium is also independent of initial debt. Let \(\tilde{V}_t(\tilde{h}^{t-1})\) denote the continuation value normalized
by the level of debt starting from a history $\tilde{h}^{t-1}$:

$$V_t(\tilde{h}^{t-1}) = V_t(\tilde{h}^{t-1}) - \frac{E_t[\theta_t]}{1-\delta} \log \left( \frac{R^\tau R - 1 - Rb_{t-1}(\tilde{h}^{t-1})}{R^\tau R - 1} \right).$$

We obtain that the highest and lowest normalized continuation values at time 0—namely the highest and lowest values of $\tilde{V}_0(b_{-1})$—are independent of the initial debt $b_{-1}$. We can thus represent these values by $\tilde{V}$ and $\tilde{V}$, and, using the definition of normalized welfare, we have

$$V(b) = \tilde{V} + \frac{E_t[\theta_t]}{1-\delta} \log \left( \frac{R^\tau R - 1 - Rb}{R^\tau R - 1} \right),$$

$$V(b) = \tilde{V} + \frac{E_t[\theta_t]}{1-\delta} \log \left( \frac{R^\tau R - 1 - Rb}{R^\tau R - 1} \right).$$

It follows that $\tilde{V}(\cdot)$ and $V(\cdot)$ are continuously differentiable, strictly decreasing, and strictly concave. Moreover, given the constants $\tilde{V} \geq \tilde{V}$, we have

$$\tilde{V}(b) - \tilde{V}(b) = \tilde{V} - \tilde{V} \equiv P^*,$$

where $P^* \geq 0$ is independent of $b$, and is finite given that the set of feasible policies is closed and payoffs are thus bounded.

Lastly, observe that by the arguments above, programs $(P_{\text{max}})$ and $(P_{\text{min}})$ characterizing the values $\tilde{V}(b_{-1})$ and $V(b_{-1})$ can be represented using savings rates $s(\theta)$ and normalized continuation values $\tilde{V}(s(\theta))$, where the lowest and highest such values, $\tilde{V}$ and $\tilde{V}$, are independent of initial debt. It follows that if $\tilde{V} > \tilde{V}$, then the interior solutions to $(P_{\text{max}})$ and $(P_{\text{min}})$ are given by thresholds $\{\theta^*, \theta^{**}\}$ and $\{\theta^*_n, \theta^{**n}\}$ that are also independent of initial debt.

### B.2 Proof of Proposition 4

Note that by (B.1)-(B.2) and the definitions of $b^r(\omega, \theta)$ and $b^p(\omega, \theta)$, we have $b^r(\omega, \theta) = b^p(\omega, \theta)$ for all $\omega$ and $\theta$, independent of the value of $P^* = \tilde{V}(b_{-1}) - \tilde{V}(b_{-1})$. Let $b^l(\theta) \equiv b^r(\omega, \theta) = b^p(\omega, \theta)$ and $g^l(\theta) \equiv b^l(\theta) + \omega$, where we omit the dependence on $\omega$ to reduce notation. We proceed in four steps.

**Step 1.** Suppose there is an interior equilibrium with fiscal regimes characterized by maximally enforced deficit and surplus limits as defined in Definition 1 and Defini-
tion 2, with cutoffs \( \{\theta^*, \theta^{**}, \theta^*_n, \theta^{**}_n\} \) and value of punishment \( P^* = \bar{V}(b_{-1}) - \underline{V}(b_{-1}) \).

We show that this equilibrium satisfies the system of equations (18)-(20).

To obtain (18), take condition (13) in Definition 1. Integrating its left- and right-hand sides, we can rewrite this condition as

\[
\alpha \theta^* U(g^f(\theta^*)) + \delta V(b^f(\theta^*)) + \alpha \int_{\theta^*}^{\theta^{**}} U(g^f(\theta)) d\theta = \alpha \theta^* U(g^f(\theta^*)) + \delta V(b^f(\theta^*)) + \alpha \int_{\theta^*}^{\theta^{**}} U(g^f(\theta)) d\theta.
\]

By (B.3), this equality simplifies to (18). Analogous steps yield that condition (15) in Definition 2 can be rewritten as (19). Finally, to obtain (20), we can use the representation of welfare in (10) to write

\[
\bar{V}(b) = \lim_{\theta' \to 0} \left[ \alpha \theta' U(g^f(\theta')) + \delta V(b^f(\theta')) \right] + \int_{\theta'}^{\theta^{**}} \alpha U(g^f(\theta)) Q(\theta) d\theta
\]

\[
\underline{V}(b) = \lim_{\theta' \to 0} \left[ \alpha \theta' U(g^f(\theta')) + \delta V(b^f(\theta')) \right] + \int_{\theta'}^{\theta^{**}} \alpha U(g^f(\theta)) Q(\theta) d\theta
\]

where \( Q(\theta) = 1 \) for \( \theta < \bar{\theta} \) and \( Q(\theta) = 0 \) for \( \theta > \bar{\theta} \). Subtracting the bottom equation from the top one and again using (B.3) yields (20).

**Step 2.** Consider the program given by (21)-(23). Let \( P^* \) be the largest value of \( P \) that admits \( T(P) = P \) and suppose \( P^* > 0 \). We show that \( P^* \geq \bar{V}(b_{-1}) - \underline{V}(b_{-1}) \). Moreover, there exists a sufficiently large feasible set \( [b(b_{-1}), \bar{b}(b_{-1})] \) such that \( \{\bar{V}(b_{-1}), \underline{V}(b_{-1})\} \) are supported by interior allocations and \( P^* = \bar{V}(b_{-1}) - \underline{V}(b_{-1}) \).

Step 2a. Consider a solution to (21)-(23) for some \( P > 0 \). We show that there exists such a solution that admits (22) and (23) with equality.

Suppose first that (22) holds as a strict inequality in the solution. The derivative of (21) with respect to \( \theta^{**} \) takes the same sign as \( -Q(\theta^{**}) \). By Assumption 2 and \( f(\bar{\theta}) = 0 \), we have \( -Q(\theta) \) strictly negative for low \( \theta \) and strictly positive for high \( \theta \) given \( \theta < \bar{\theta} \), and we have \( Q(\theta) = 0 \) given \( \theta \geq \bar{\theta} \). Thus, the solution admits either \( \theta^* = \theta^{**} \) or \( \theta^{**} \geq \bar{\theta} \).
We show that the solution cannot have $\theta^* = \theta^{**}$. Suppose $\theta^* = \theta^{**}$ and consider first the case that $Q(\theta^{**}) < 0$. We can perform a perturbation that increases $\theta^{**}$ until either constraint (22) holds as an equality or $\theta^{**} = \overline{\theta}$. This perturbation increases the value of $\int_{\theta^*}^{\theta^{**}} [U(g(\theta^*)) - U(g(\theta))] Q(\theta) d\theta$ in the objective while satisfying all constraints, thus yielding a contradiction. Take next the case that $Q(\theta^{**}) \geq 0$. We can first perform a perturbation that changes $\theta^{**}$ and $\theta^*$ by the same amount $\Delta \geq 0$, which does not affect the objective nor the constraints (since $\theta^* = \theta^{**}$), and then we can perform the same perturbation as above starting from the new values. By choosing $\Delta$ such that $Q(\theta^{**} + \Delta) < 0$, we obtain again that the perturbation increases the value of the objective while satisfying all constraints, thus yielding a contradiction.

It follows from the above claims that the solution must have $\theta^* < \theta^{**}$ and $\theta^{**} \geq \overline{\theta}$. Then the derivative of (21) with respect to $\theta^*$ implies

$$\int_{\theta^*}^{\theta^{**}} Q(\theta) d\theta = \int_{\theta^*}^{\theta^{**}} Q(\theta) d\theta = 0,$$

which yields a unique interior value of $\theta^*$ given Assumption 2. Since the optimal value of $\theta^*$ is independent of $\theta^{**}$ and $\theta^{**} \geq \overline{\theta}$, the objective in (21) is invariant to increases in $\theta^{**}$. Moreover, the right-hand side of (23) is invariant to $\theta^{**}$, while the right-hand side of (22) is rising in $\theta^{**}$. Therefore, there exists a solution to (21)-(23) that admits (22) as an equality.

Suppose next that (23) holds as a strict inequality in the solution. The derivative of (21) with respect to $\theta^{**}$ takes the same sign as $Q(\theta^{**})$. By Assumption 2 and $f(\overline{\theta}) = 0$, $Q(\theta)$ is strictly positive for low $\theta$ and strictly negative for high $\theta$ given $\theta < \overline{\theta}$, and $Q(\theta) = 0$ given $\theta > \overline{\theta}$. Thus, the optimal value of $\theta^{**}_n$ is interior and satisfies $Q(\theta^{**}_n) = 0$. Now consider the optimal value of $\theta^*_n$. The derivative of (21) with respect to $\theta^*_n$ is proportional to $-\int_{\theta^*_n}^{\theta^{**}_n} Q(\theta) d\theta$. Since $Q(\theta) < 0$ for all $\theta \in (\theta^{**}_n, \overline{\theta})$, it follows that $-\int_{\theta^*_n}^{\theta^{**}_n} Q(\theta) d\theta > 0$ for all $\theta^*_n$, and thus the value of $\theta^*_n$ that maximizes the objective is unbounded from above. Since the right-hand side of (23) approaches $\infty$ as $\theta^*_n \to \infty$, it follows that (23) must hold with equality in the solution.

Step 2b. We show that if the largest value $P^*$ that admits $T(P^*) = P^*$ satisfies $P^* > 0$, then $P^* \geq \overline{V}(b_{-1}) - \overline{V}(b_{-1})$, with equality if $[b(b_{-1}), \overline{b}(b_{-1})]$ is sufficiently large that $\{\overline{V}(b_{-1}), \overline{V}(b_{-1})\}$ are supported by interior allocations.

Fix $P > 0$ and consider programs $(\mathcal{P}_{\text{max}})$ and $(\mathcal{P}_{\text{min}})$, defining $\overline{V}(b_{-1})$ and $\overline{V}(b_{-1})$ respectively, with the constraint that the highest and lowest feasible continuation
values satisfy $V(b(\theta)) - \bar{V}(b(\theta)) = P$. By the arguments in Subsection B.1, we can represent these programs using savings rates $s(\theta)$ and normalized continuation values $\bar{V}(s(\theta))$, where the lowest and highest normalized continuation values $\bar{V}$ and $\bar{V}$ are independent of initial debt and satisfy $\bar{V} - \bar{V} = P$. Letting $\bar{P}(s(\theta)) \equiv \bar{V}(s(\theta)) - \bar{V}$, the limited commitment constraint (8) using such a representation can be written as

$$\alpha \theta \log(1 - s(\theta)) + \frac{\delta}{1 - \delta} \mathbb{E}[\theta] \log(s(\theta)) + \delta \bar{P}(s(\theta)) \geq \alpha \theta \log(1 - s^f(\theta)) + \frac{\delta}{1 - \delta} \mathbb{E}[\theta] \log(s^f(\theta)), \quad (B.4)$$

where $s(\theta) \in [\underline{s}, \bar{s}]$, and $\bar{P}(s(\theta)) \in [0, P]$.

We claim that if the feasible set $[\underline{s}, \bar{s}]$ is large enough, then the solutions to programs $(P_{\text{max}})$ and $(P_{\text{min}})$ conditional on $\bar{V} - \bar{V} = P$ must be interior. Suppose by contradiction that this is not the case. Observe that given $\bar{P}(s(\theta)) \in [0, P]$, the left-hand side of constraint (B.4) approaches $-\infty$ as $s(\theta)$ approaches either 0 or 1. Thus, if the allocation is at the boundaries of the set $[\underline{s}, \bar{s}]$, the constraint is violated for $[\underline{s}, \bar{s}]$ large enough, yielding a contradiction.

It follows that for sufficiently large $[\underline{s}, \bar{s}]$ and $\bar{V} - \bar{V} = P > 0$, programs $(P_{\text{max}})$ and $(P_{\text{min}})$ admit interior allocations and Proposition 2 and Proposition 3 hold. Thus, conditional on $P > 0$, the highest value $V(b_{-1})$ must be bounded from above by the the solution to $(P_{\text{max}})$ satisfying Definition 1, and the lowest value $V(b_{-1})$ must be bounded from below by the solution to $(P_{\text{min}})$ satisfying Definition 2. The claim then follows from Step 1, the definition of $T(P)$, and Step 2a.

**Step 3.** We show that $T(P)$ has the following properties: $T'(P) > 0$; $T''(P) < 0$; $\lim_{P \to \infty} T'(P) < 1$; and

$$\lim_{P \to 0} T'(P) > (\leftarrow)1 \text{ if } 1 + 2 \frac{\delta}{1 - \delta} Q(\hat{\theta}) < (\rightarrow)0. \quad (B.5)$$

Step 3a. We show that any solution to (21)-(23) for $P > 0$ is interior. Consider first $\{\theta^*, \theta^{**}\}$. Suppose that $\theta^* = 0$. Then (22) would be violated since $U(g^f(0)) = -\infty$, unless $\theta^{**} = \theta^*$, but in that case (22) would be a strict inequality, violating Step 2a. Therefore, $\theta^* > 0$. Analogous arguments imply that $\theta^{**}$ is finite. Since $\theta^* < \theta^{**}$ (by (22) binding in the solution), it follows that both $\theta^*$ and $\theta^{**}$ are interior.

Consider next $\{\theta^*_n, \theta^{**}_n\}$. Suppose that $\theta^*_n = \infty$. Then (23) would be violated since
\( U(g_f(\infty)) = \infty \), unless \( \theta_n^{**} = \theta_n^* \), but in that case (23) would be a strict inequality, violating Step 2a. Therefore, \( \theta_n^* \) is finite. Suppose next that \( \theta_n^{**} = 0 \). Then necessarily \( \theta_n^* > 0 \), since otherwise (23) would be a strict inequality, violating Step 2a. Consider an increase in \( \theta_n^{**} \) by \( \varepsilon > 0 \) arbitrarily small. The change in the objective in (21) is proportional to \( Q(\theta_n^{**}) = 1 > 0 \). Constraint (22) is unchanged, whereas constraint (23) is relaxed as its right-hand side decreases. Therefore, \( \theta_n^{**} > 0 \). Since \( \theta_n^{**} < \theta_n^* \) (by (23) binding in the solution), it follows that both \( \theta_n^{**} \) and \( \theta_n^* \) are interior.

Step 3b. We show that the solution to (21)-(23) is unique. Let \( \mu^R \geq 0 \) and \( \mu^P \geq 0 \) denote the Lagrange multipliers on (22) and (23). By Step 3a, the solution is characterized by the following first-order conditions:

\[
\int_{\theta^*}^{\theta^{**}} Q(\theta) d\theta = -\mu^R \int_{\theta^*}^{\theta^{**}} 1 d\theta \tag{B.6}
\]

\[
Q(\theta^{**}) = -\mu^R \tag{B.7}
\]

\[
\int_{\theta_n^*}^{\theta_n^{**}} Q(\theta) d\theta = -\mu^P \int_{\theta_n^*}^{\theta_n^{**}} 1 d\theta \tag{B.8}
\]

\[
Q(\theta_n^{**}) = -\mu^P. \tag{B.9}
\]

Conditions (B.6) and (B.7) imply

\[
\int_{\theta^*}^{\theta^{**}} [Q(\theta) - Q(\theta^{**})] d\theta = 0. \tag{B.10}
\]

Observe that the derivative of the left-hand side with respect to \( \theta^* \) is \(-(Q(\theta^*) - Q(\theta^{**}))\), and the derivative of the left-hand side with respect to \( \theta^{**} \) is \(-\int_{\theta^*}^{\theta^{**}} Q'(\theta^{**})d\theta\). Both of these are negative given Assumption 2 and (B.10), so condition (B.10) defines a decreasing relationship between \( \theta^* \) and \( \theta^{**} \). Now consider constraint (22) which holds with equality by Step 2a. The right-hand side of (22) is increasing in \( \theta^{**} \) but decreasing in \( \theta^* \), so (22) defines an increasing relationship between \( \theta^* \) and \( \theta^{**} \). It follows that the values of \( \theta^* \) and \( \theta^{**} \) are uniquely pinned down by (22) and (B.10).

Conditions (B.8) and (B.9) imply

\[
\int_{\theta_n^*}^{\theta_n^{**}} [Q(\theta_n^{**}) - Q(\theta)] d\theta = 0. \tag{B.11}
\]

By analogous arguments to those used above, this condition defines a decreasing relationship between \( \theta_n^{**} \) and \( \theta_n^* \), whereas constraint (23), which holds with equality
by Step 2a, defines an increasing relationship between $\theta^*_n$ and $\theta^{**}_n$. It follows that the values of $\theta^*_n$ and $\theta^{**}_n$ are uniquely pinned down by (23) and (B.11).

**Step 3c.** We show that $T'(P) > 0$. By the Envelope condition,

$$T'(P) = \delta \left(1 + \mu^R + \mu^P\right) = \delta \left(1 - Q(\theta^{**}) - Q(\theta^{**}_n)\right),$$

(B.12)

where the second equality follows from (B.7) and (B.9). Given Assumption 2, conditions (B.10) and (B.11) imply that $\theta^* < \hat{\theta} < \theta^{**}$, $\theta^{**}_n > \hat{\theta} > \theta^{**}_n$, $Q(\theta^{**}) < 0$, and $Q(\theta^{**}_n) < 0$. Therefore, (B.12) implies $T'(P) > 0$.

**Step 3d.** We show that $T''(P) < 0$. From Step 3c,

$$T''(P) = \delta \left(-Q'(\theta^{**}) \frac{d\theta^{**}}{dP} - Q'(\theta^{**}_n) \frac{d\theta^{**}_n}{dP}\right)$$

(where recall that $Q(\theta)$ is differentiable everywhere given $f(\theta) = f(\hat{\theta}) = 0$). Assumption 2, (B.10) and (B.11) imply that $Q'(\theta^{**}) > 0$ and $Q'(\theta^{**}_n) < 0$. To prove that $T''(P) < 0$, it is therefore sufficient to prove that $d\theta^{**}/dP > 0$ and $d\theta^{**}_n/dP < 0$.

Consider first $d\theta^{**}/dP$. A higher value of $P$ means that a strictly higher value of $\theta^{**}$ is required to satisfy (22) with equality for every value of $\theta^*$. Given the decreasing relationship between $\theta^*$ and $\theta^{**}$ defined by condition (B.10), it follows that a higher value of $P$ is associated with a lower value of $\theta^*$ and a higher value of $\theta^{**}$. Thus, $d\theta^{**}/dP > 0$.

Consider next $d\theta^{**}_n/dP$. A higher value of $P$ means that a lower value of $\theta^{**}_n$ is required to satisfy (23) with equality for every value of $\theta^*_n$. Given the decreasing relationship between $\theta^*_n$ and $\theta^{**}_n$ defined by condition (B.11), it follows that a higher value of $P$ is associated with a higher value of $\theta^*_n$ and a lower value of $\theta^{**}_n$. Thus, $d\theta^{**}_n/dP < 0$.

**Step 3e.** We show that $\lim_{P \to \infty} T'(P) < 1$. Using (B.12), observe that if $\mu^R$ and $\mu^P$ each approach 0 as $P \to \infty$, then $T'(P)$ approaches $\delta < 1$. To prove the claim, it is thus sufficient to prove that $\mu^R$ and $\mu^P$ each approach 0 as $P \to \infty$.

We first show that $\mu^R = 0$ for $P$ sufficiently large. Consider the solution to the relaxed problem in (21) that ignores constraint (22). The first-order conditions (B.6)
and (B.7) imply $\theta^{**} \geq \bar{\theta}$ and $\theta^* = \theta_e$ for $\theta_e$ defined by
\[
\int_{\theta_e}^{\bar{\theta}} Q(\theta) d\theta = 0. \quad (B.13)
\]
It follows that if
\[
\delta P \geq \alpha \int_{\theta_e}^{\bar{\theta}} \left[ U(g^f(\theta)) - U(g^f(\theta_e)) \right] d\theta,
\]
then this solution satisfies (22) for some $\theta^{**} \geq \bar{\theta}$. Therefore, the solution to the relaxed problem solves the original problem, implying $\mu^R = 0$ for $P$ sufficiently large.

We next show that $\mu^P \to 0$ as $P \to \infty$. From Assumption 2 and (B.11), $Q(\theta^{**}_n) < 0$, implying that $\theta^{**}_n$ is strictly bounded from below. It follows that for (23) to hold as an equality, it must be that $\theta^*_n \to \infty$ as $P \to \infty$. We can then rewrite condition (B.11) as
\[
\int_{\theta^{**}_n}^{\theta^*_n} [Q(\theta^{**}_n) - Q(\theta)] d\theta = (\theta^*_n - \theta^{**}_n) Q(\theta^{**}_n) - \int_{\theta^{**}_n}^{\bar{\theta}} Q(\theta) d\theta = 0.
\]
Substituting with (B.9) and rearranging terms yields
\[
\mu^P = -\frac{\int_{\theta^{**}_n}^{\bar{\theta}} Q(\theta) d\theta}{\theta^*_n - \theta^{**}_n}.
\]
As $P \to \infty$ and thus $\theta^*_n \to \infty$, the numerator is bounded whereas the denominator grows unboundedly. Thus, $\mu^P \to 0$ as $P \to \infty$.

**Step 3f.** We show that $T(P)$ has the property stated in (B.5). Given Assumption 2, conditions (B.10) and (B.11) require $\theta^* < \hat{\theta} < \theta^{**}$ and $\theta^*_n > \hat{\theta} > \theta^{**}_n$. Therefore, satisfaction of (22) and (23) implies that $\theta^*, \theta^{**}, \theta^*_n$ and $\theta^{**}_n$ each approach $\hat{\theta}$ as $P \to 0$. Using (B.12), it thus follows that
\[
\lim_{P \to 0} T'(P) = \delta(1 - 2Q(\hat{\theta})),
\]
and therefore $\lim_{P \to 0} T'(P) > (\leq)1$ if $1 + 2\frac{\delta}{1-\delta}Q(\hat{\theta}) < (>)0$.

**Step 4.** We prove the claim in the proposition.

Observe that $T(0) = 0$, and by continuity, $\lim_{P \to 0} T(P) = 0$. Consider the condi-
tion given in Step 3:

\[ 1 + 2 \frac{\delta}{1 - \delta} Q(\hat{\theta}) < 0. \] (B.14)

Suppose first that (B.14) holds. Then by Step 3, the shape of \( T(P) \) implies that there exists a unique value \( P^* > 0 \) such that \( T(P^*) = P^* \). By Step 2b, for a sufficiently large feasible set \([\underline{s}, \overline{s}]\), the values \( \overline{V}(\cdot) \) and \( \underline{V}(\cdot) \) are supported by interior allocations and satisfy \( \overline{V}(\cdot) - \underline{V}(\cdot) = P^* \), implying \( \overline{V}(\cdot) > \underline{V}(\cdot) \).

Suppose next that (B.14) does not hold. Then by Step 3, the largest value \( P^* \) that admits \( T(P^*) = P^* \) is \( P^* = 0 \). By Step 2b, \( P^* \geq \underline{V}(\cdot) - \overline{V}(\cdot) \) for all \( P^* > 0 \). Hence, by continuity, we must have \( \overline{V}(\cdot) = \underline{V}(\cdot) \).

Given the above claims, all is left to show is that (B.14) holds if and only if \( \delta > \tilde{\delta} \) and \( \alpha > \tilde{\alpha} \). Observe that the left-hand side of this condition is strictly decreasing in \( \alpha \). Let \( \tilde{\delta} \in (0, 1) \) be the discount factor that sets the left-hand-side equal to 0 when \( \alpha \to \infty \):

\[ 1 + 2 \frac{\delta}{1 - \delta} (1 - F(\hat{\theta}) \hat{f}(\hat{\theta})) = 0, \]

for \( \hat{\theta} \) satisfying \( \hat{\theta} f'(\hat{\theta})/f(\hat{\theta}) = -2 \). Then if \( \delta \leq \tilde{\delta} \), condition (B.14) is violated for all \( \alpha \geq 1 \). If instead \( \delta > \tilde{\delta} \), we can find a finite value \( \tilde{\alpha} \geq 1 \) such that the left-hand side of (B.14) equals 0, so that condition (B.14) holds for \( \alpha > \tilde{\alpha} \) and is violated for \( \alpha \leq \tilde{\alpha} \). Observe that since the left-hand side of (B.14) is increasing in \( \delta \), such a value \( \tilde{\alpha} \) is decreasing in \( \delta \).

**B.3 Proof of Corollary 1**

By Proposition 4, given \( \delta > \tilde{\delta} \) and \( \alpha > \tilde{\alpha} \), the best equilibrium has fiscal regimes characterized by maximally enforced deficit and surplus limits as defined in Definition 1 and Definition 2, with cutoffs \( \{\theta^*, \theta^{**}, \theta^*_n, \theta^{**}_n\} \) and value of punishment \( P = \overline{V}(b_{-1}) - \underline{V}(b_{-1}) \). Moreover, as claimed in Step 3f in the proof of Proposition 4, we must have \( \theta^* < \hat{\theta} < \theta^{**} \), where \( \hat{\theta} \in (\underline{\theta}, \overline{\theta}) \) in this environment, and where \( \theta^* \) and \( \theta^{**} \) each approach \( \hat{\theta} \) as \( P \to 0 \). The corollary then follows from the fact that, given \( \delta > \tilde{\delta} \) and \( \alpha > \tilde{\alpha} \), we have \( P \to 0 \) as \( \alpha \to \tilde{\alpha} \). Thus, there exists \( \tilde{\alpha} > \tilde{\alpha} \) such that for \( \alpha \in (\tilde{\alpha}, \tilde{\alpha}) \), \( P \) is sufficiently close to 0, and thus \( \theta^* \) and \( \theta^{**} \) are sufficiently close to \( \hat{\theta} \), that we must have \( \underline{\theta} < \theta^* < \hat{\theta} < \theta^{**} < \overline{\theta} \).